

SONOS COM.

CE Presentation
UCSB Capstone Team

Our Team

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Sponsored by: **SONOS**, **Laritech**

Our Task

To design and build a convenient communication device that works seamlessly with your existing Sonos systems.





Overview

COM. is an intercom device that can connect and control all SONOS devices in a home network.





**Communication
&
Music Control**

Capacitive Touch



Modes

- Music
- Intercom



Music Control



Intercom



User Setup Procedure



1. Power on COM.



2. Connect to WiFi network
"SONOS COM."



3. Use app to send
SSID and Password.



Design and Size Constraints

Competitor Analysis



Amazon Echo Dot

- **Advantages**

- Multiple functions
- Smart Controls
- Low price (\$49.99)

- **Disadvantages**

- Does not have a screen
- Too many buttons
- Does not have an intercom function

Weight	5.7 oz (163 grams)
Size	1.3" x 3.3" x 3.3" (32 mm x 84 mm x 84 mm)
Connectivity	Wifi
Power Source	Micro USB

Competitor Analysis

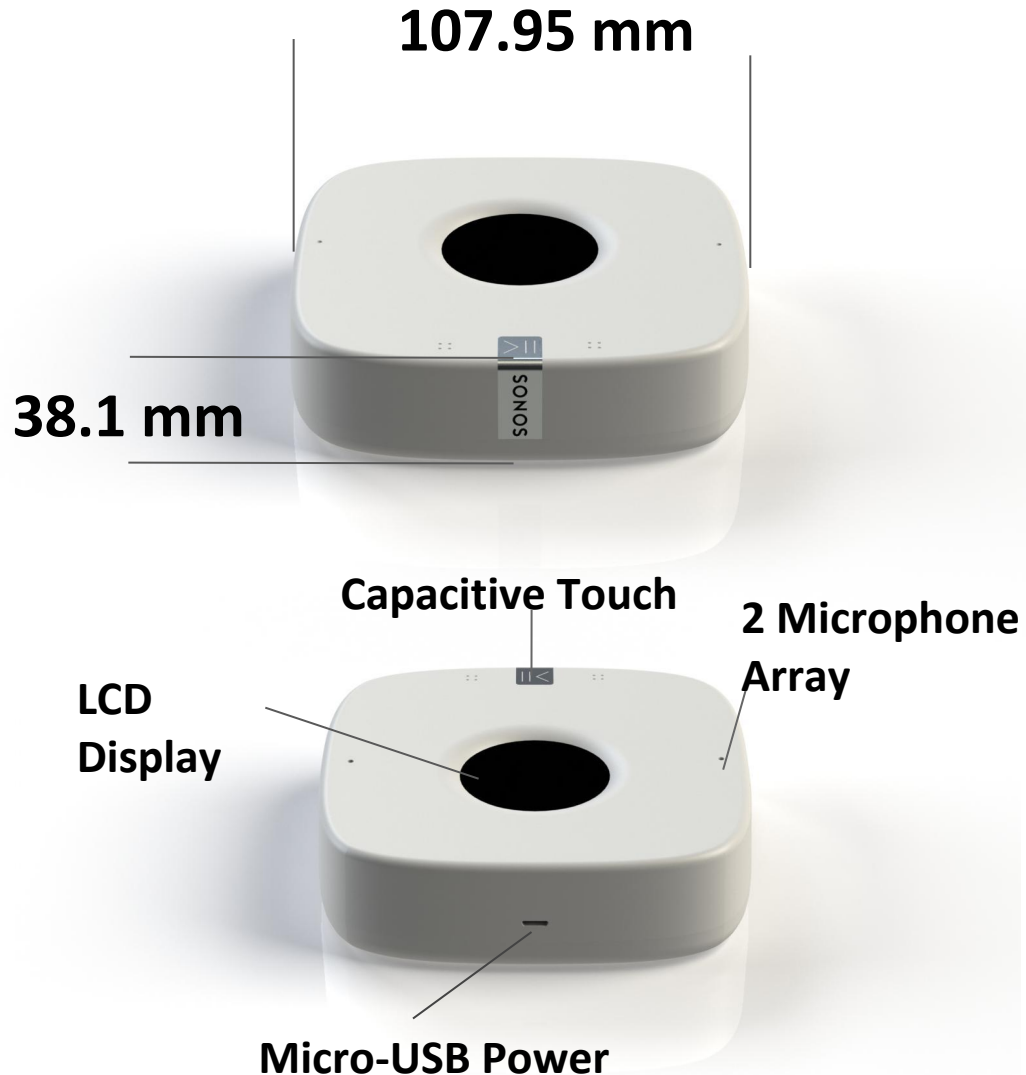


Senic Nuimo

- **Advantages**
 - Premium design
 - Rotation controls
 - Dot display
 - Can be wall mounted
- **Disadvantages**
 - Only controls music
 - Only controls single device
 - Expensive (\$199.99)

Weight	8.9 oz (254.5 grams)
Size	2.75" (70 mm) Diameter, 0.6" (15 mm) Height
Connectivity	Bluetooth LE
Power Source	Rechargeable Battery (4 months of charge) ¹⁷

Original Expected Design Specifications



Design Requirements:

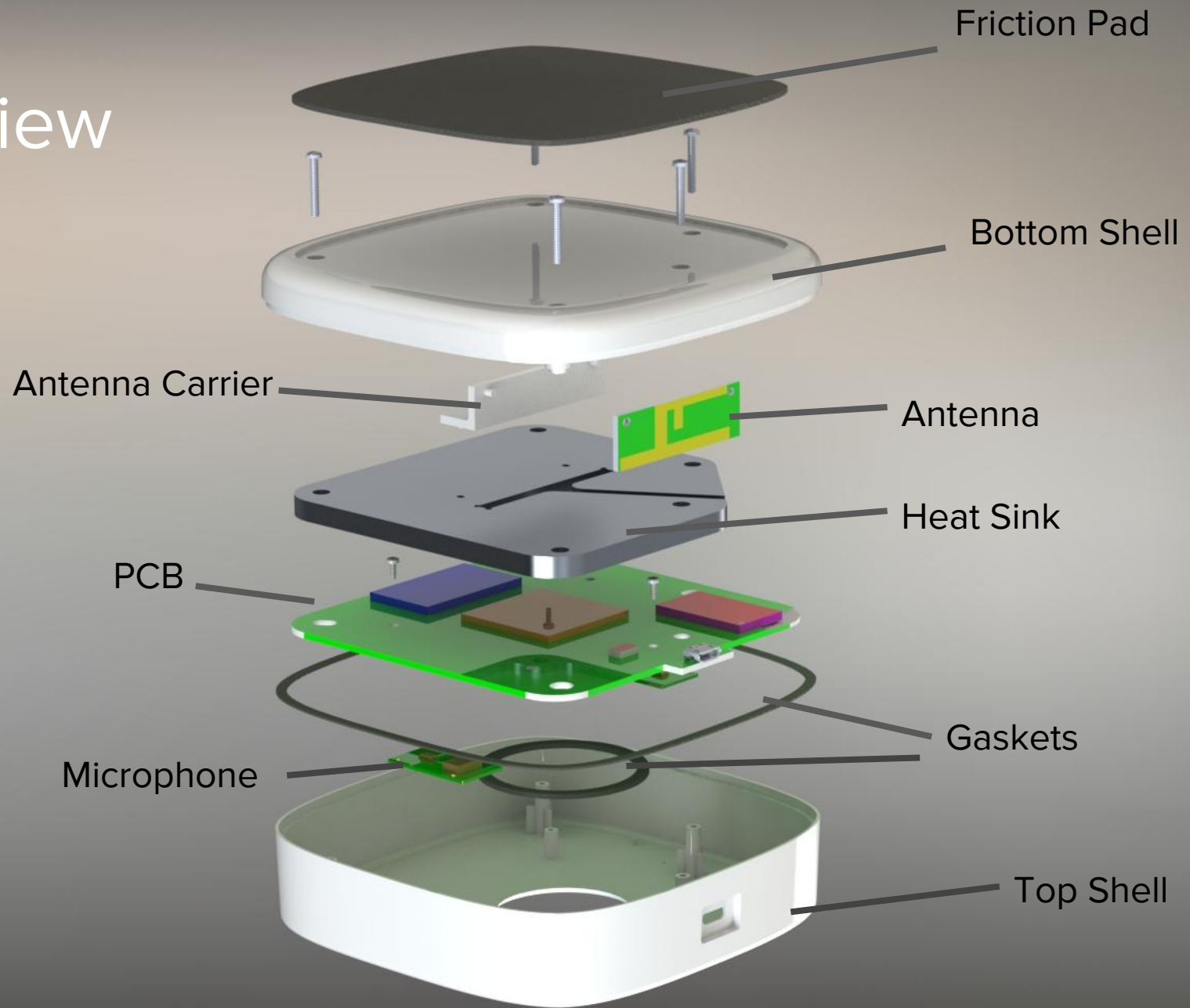
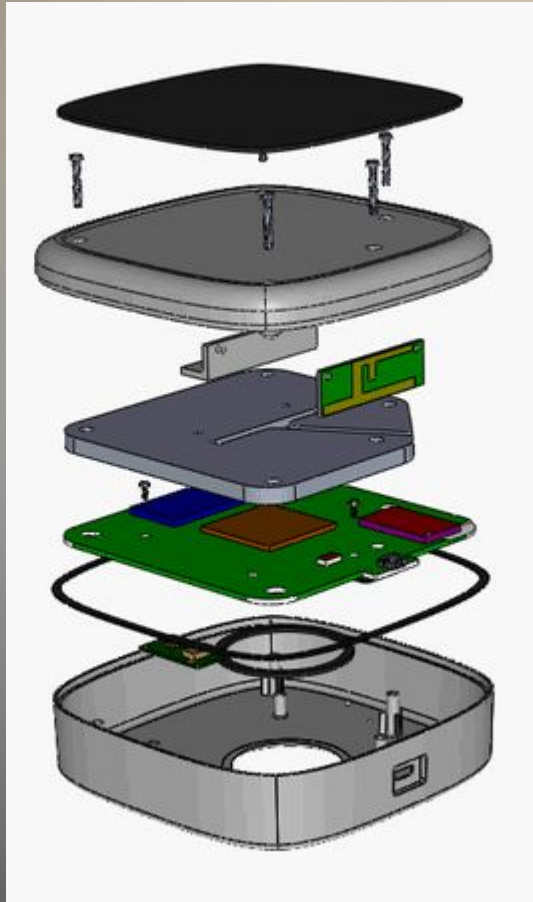
Must Design for Manufacturing, Assembly, Mass Production(Injection Molding), and for Experimentation.

Size	1.5" x 4.25" x 4.25" (38.1mm x 108mm x 108mm)
Weight	184 grams
Screen	2.2" (38 mm) Color TFT LCD Display
Material	ABS Plastic
Operating Temperature	Heat sink temperature about 55°C Shell temperature about 28~45°C
Water Protection	IP 62 (Dust tight and protection against dripping water)

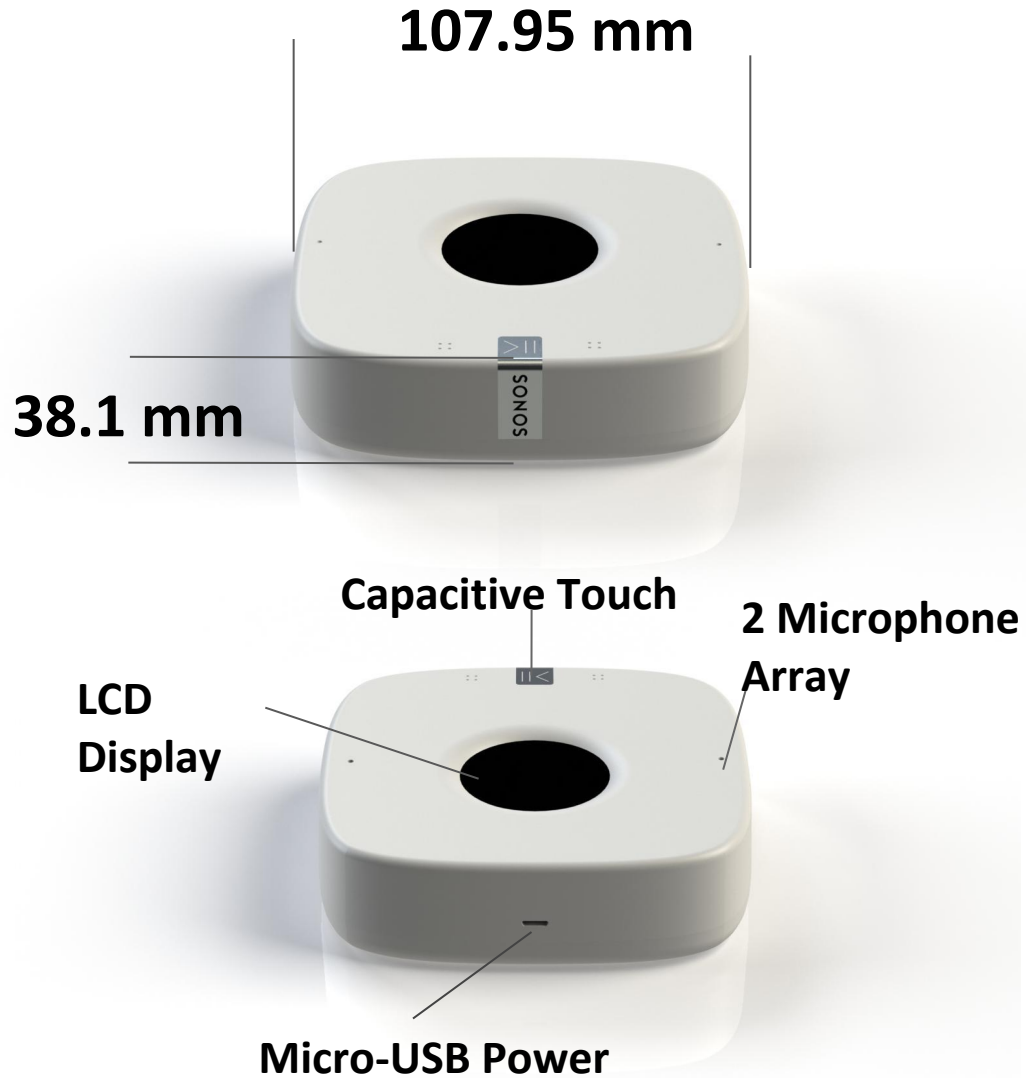
Final Design



Exploded View



Final Design Specification



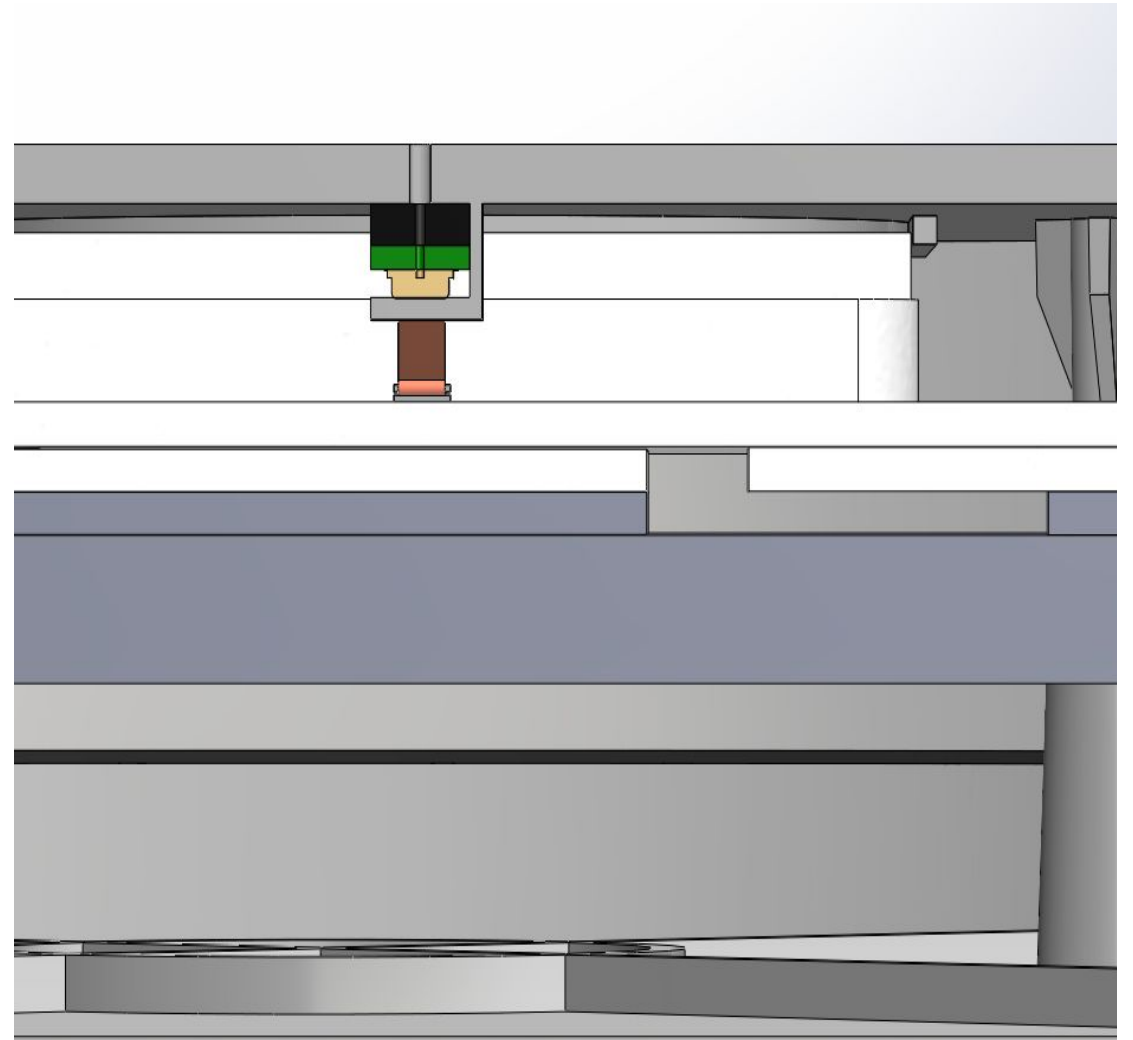
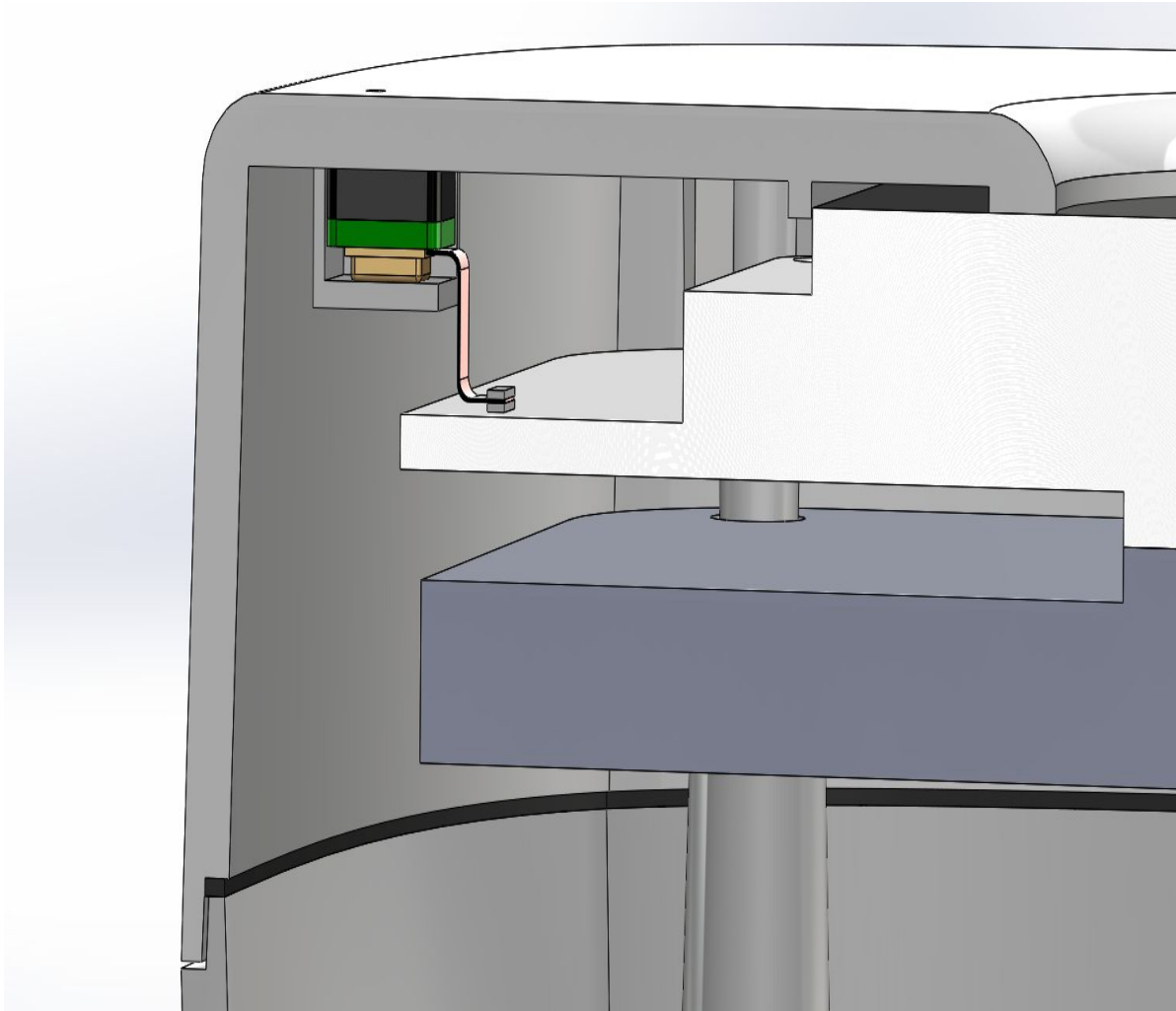
Size	1.5" x 4.25" x 4.25" (38mm x 108mm x 108mm)
Weight	248.5 grams
Screen	1.3" (33 mm) Diameter Color TFT LCD Display
Material	PC Plastic
Wi-Fi Connectivity	Wi-Fi module providing fully integrated 2.4 GHz 802.11 b/g/n radio, TCP/IP stack and a 32-bit microcontroller (MCU)
Audio	Able to seamlessly connect and control your existing SONOS home network

System Requirements	COM. comes ready to connect to your Wi-Fi. Requires an iOS or Android device compatible with the SONOS app.
Power	5V Supply via wall wart adapter to micro USB
Operating Temperature	CPU temperature ~43°C Shell temperature 26 °C
Water Protection	IP 62 (Dust tight and protection against dripping water)

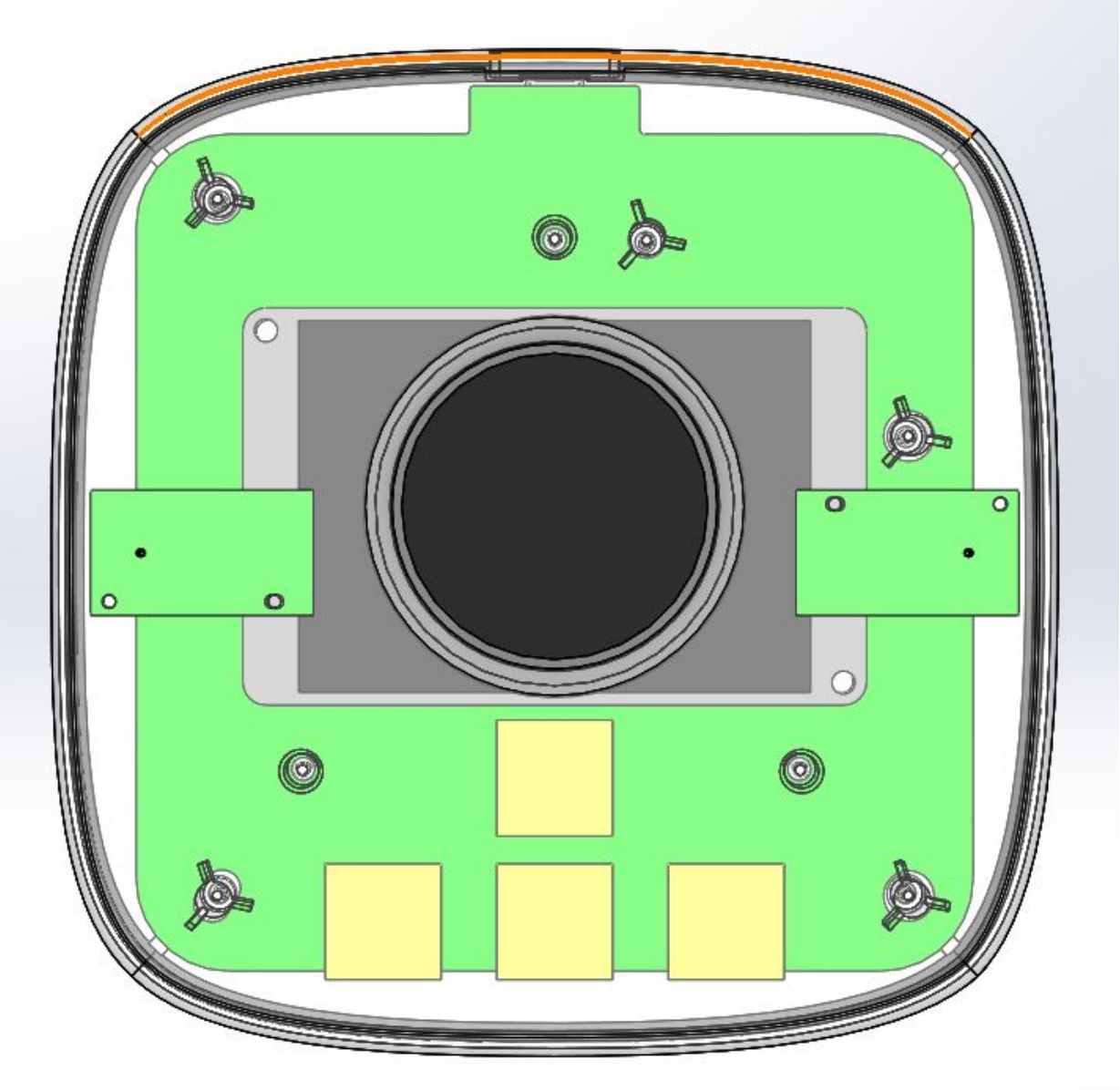
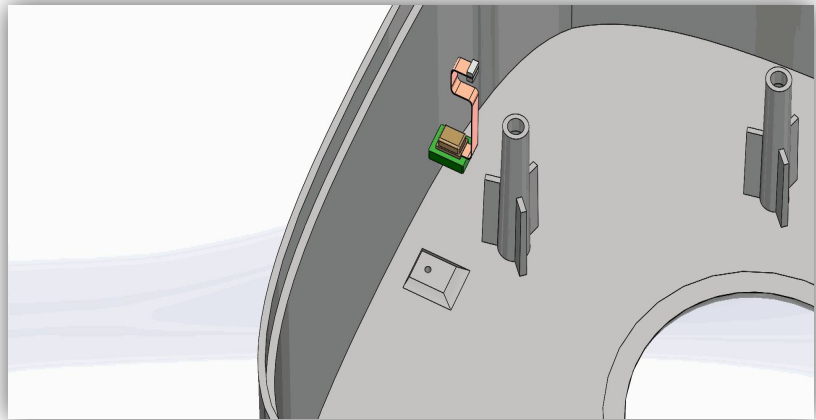
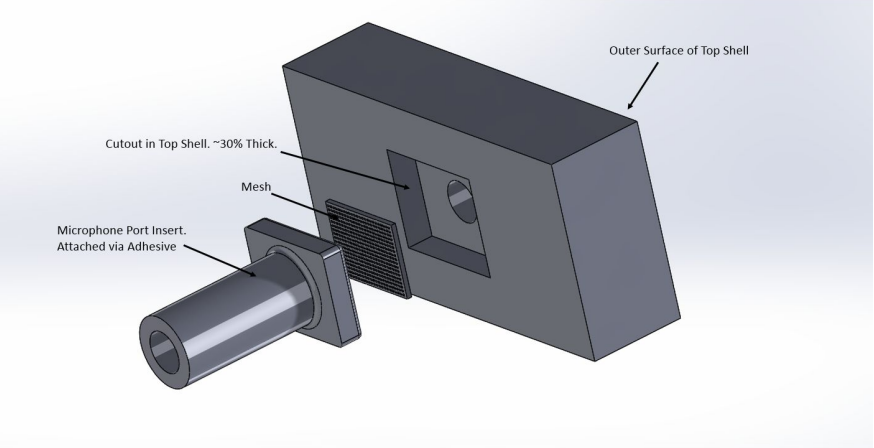


Microphone Placement Evolutions

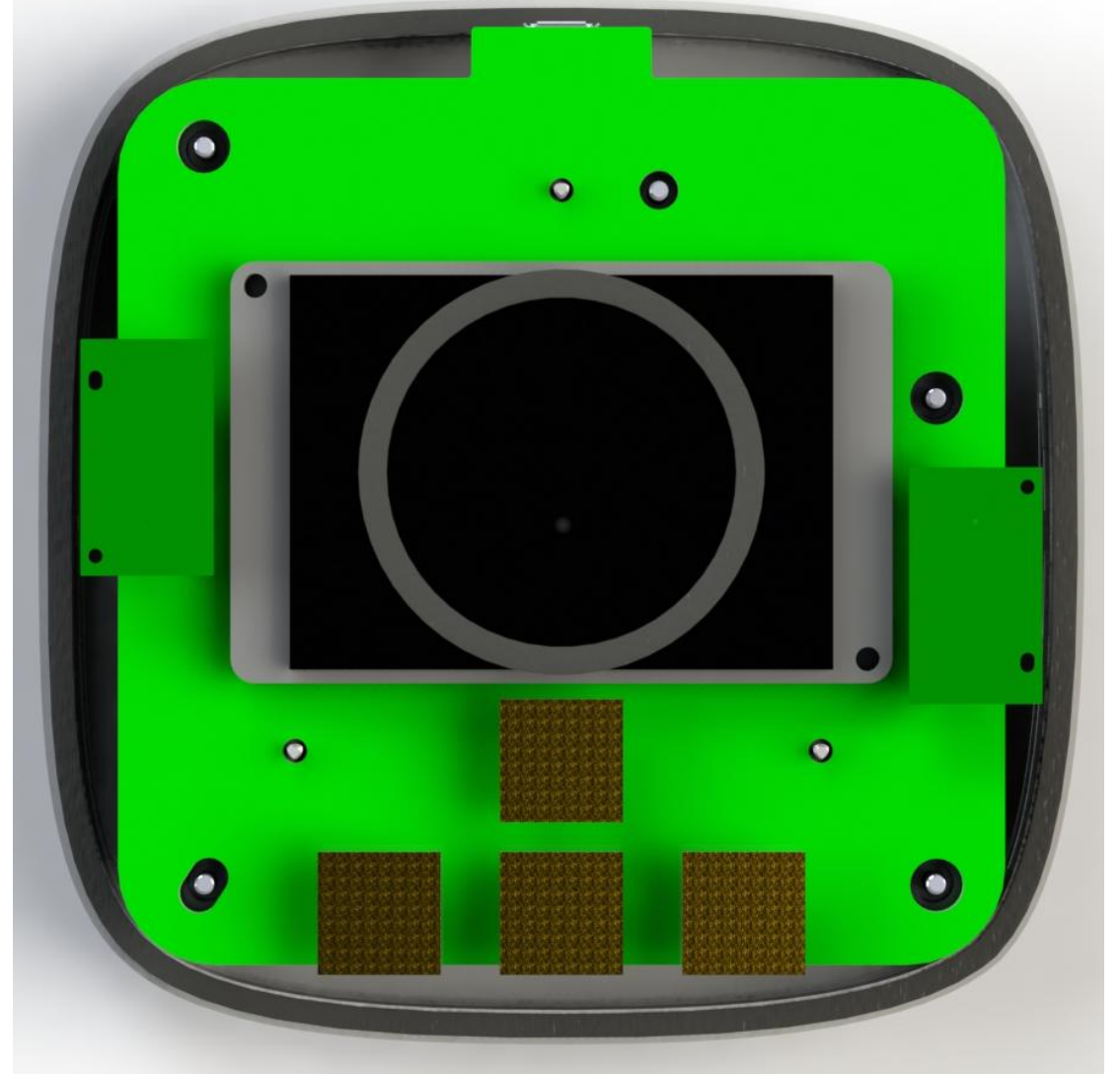
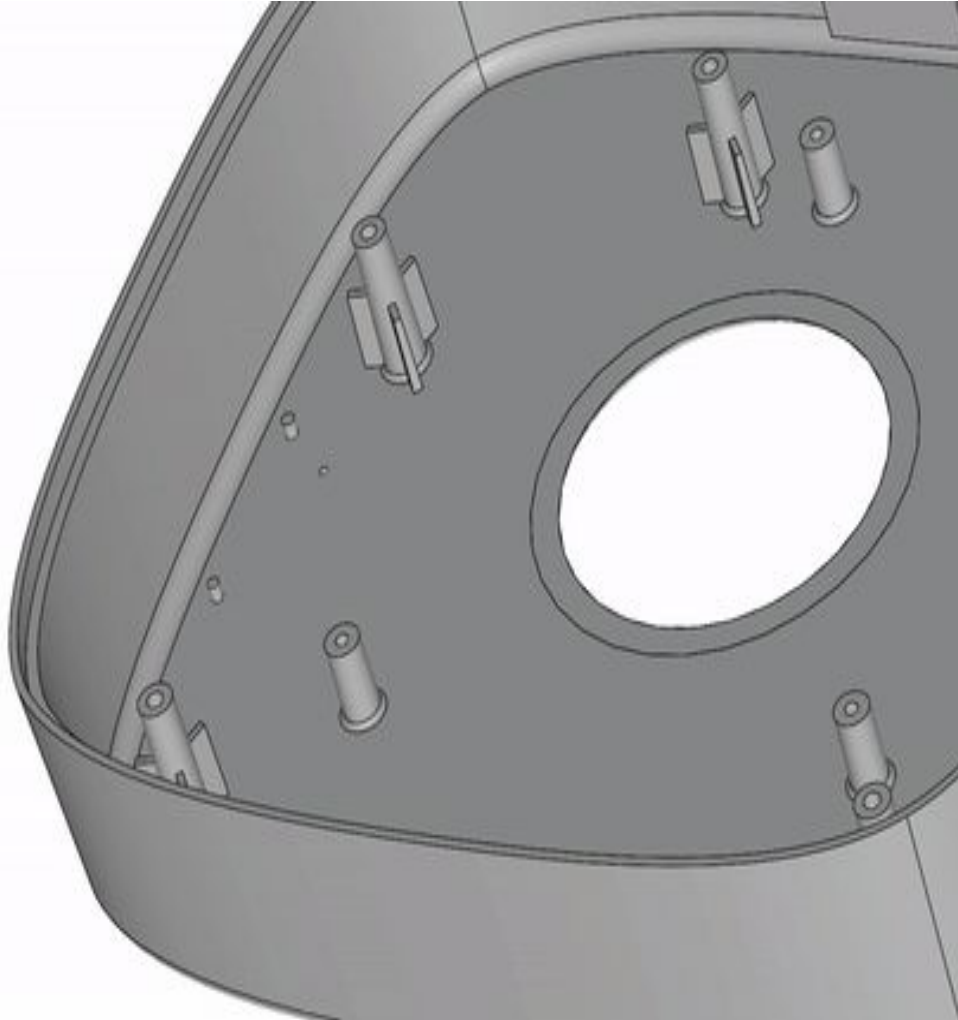
Initial Placements



Next Considerations



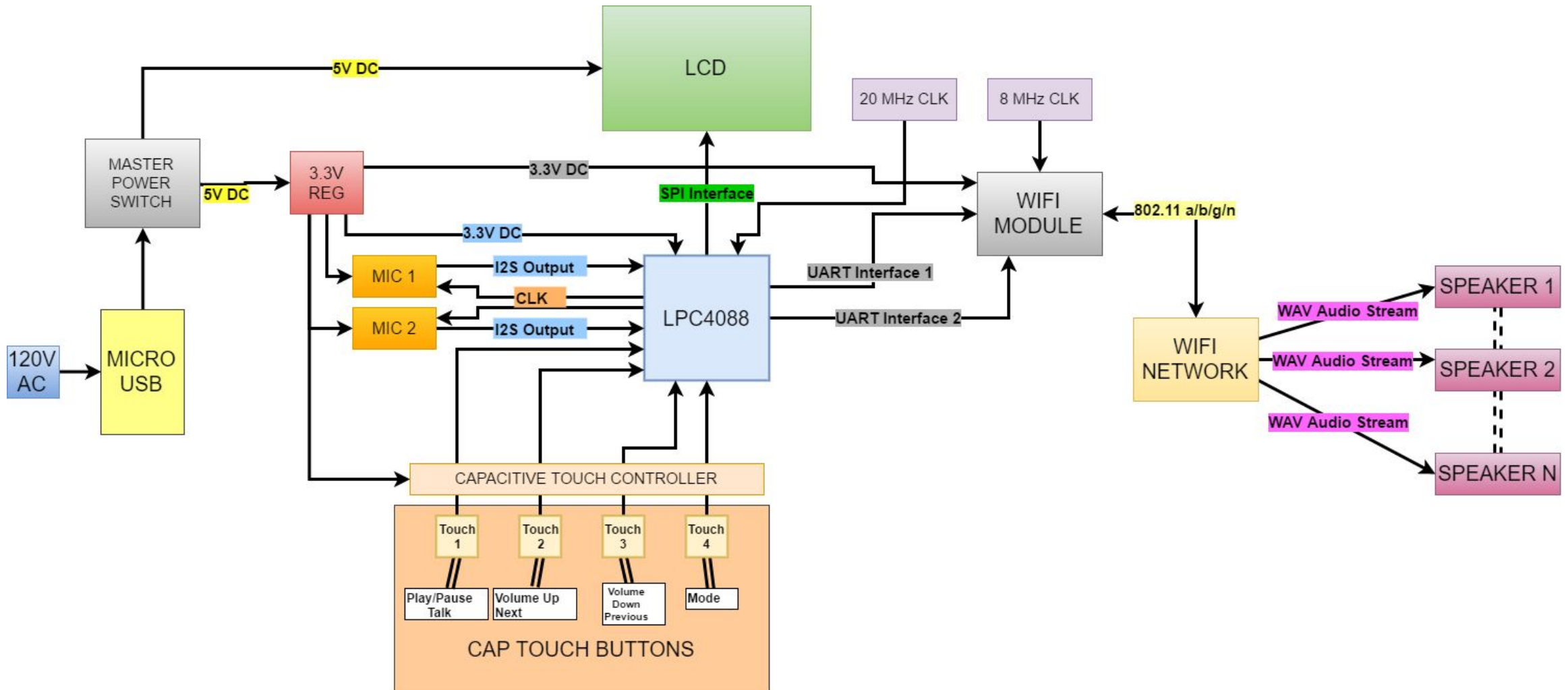
Final Placement



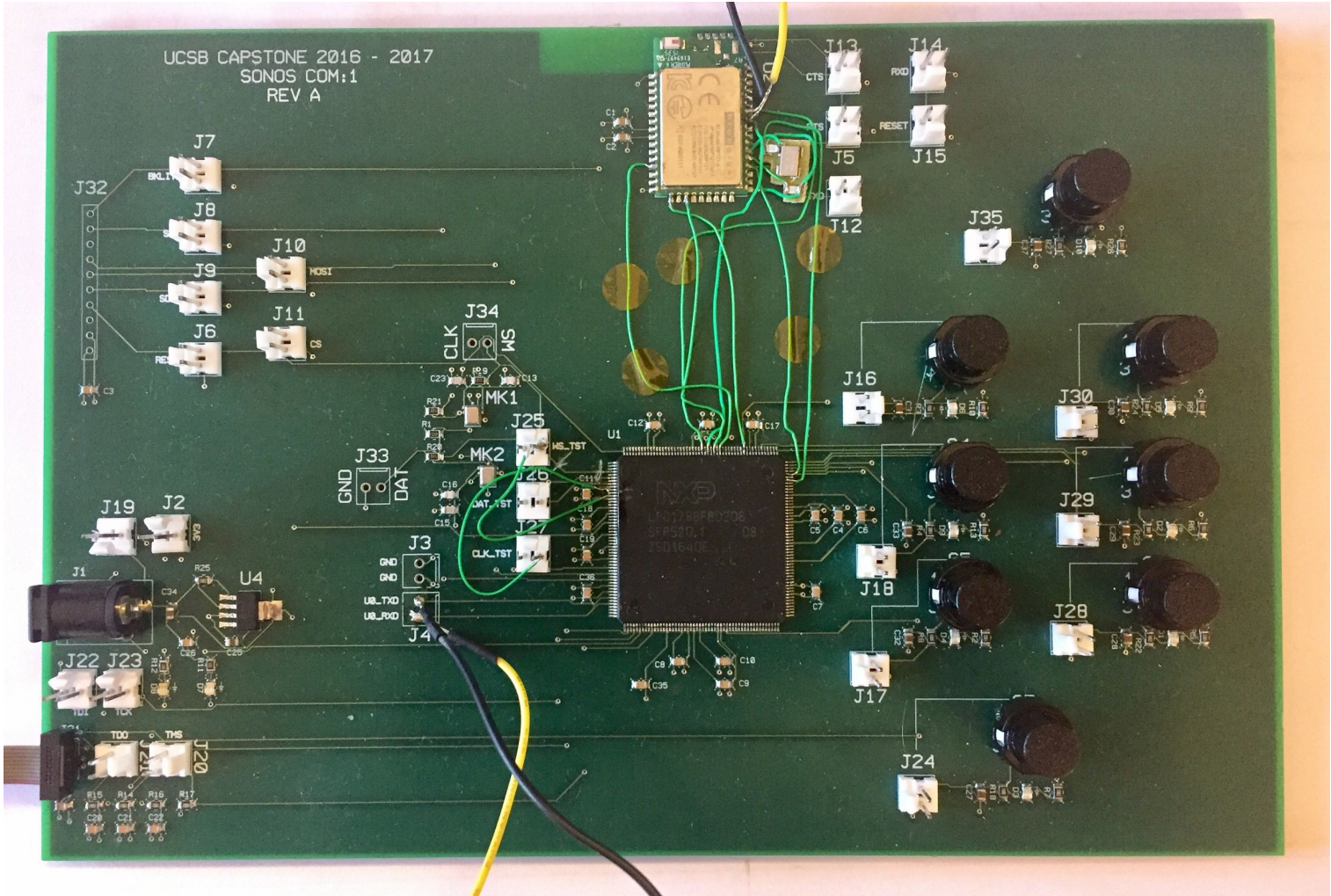


Hardware Design

Functional Hardware Block Diagram



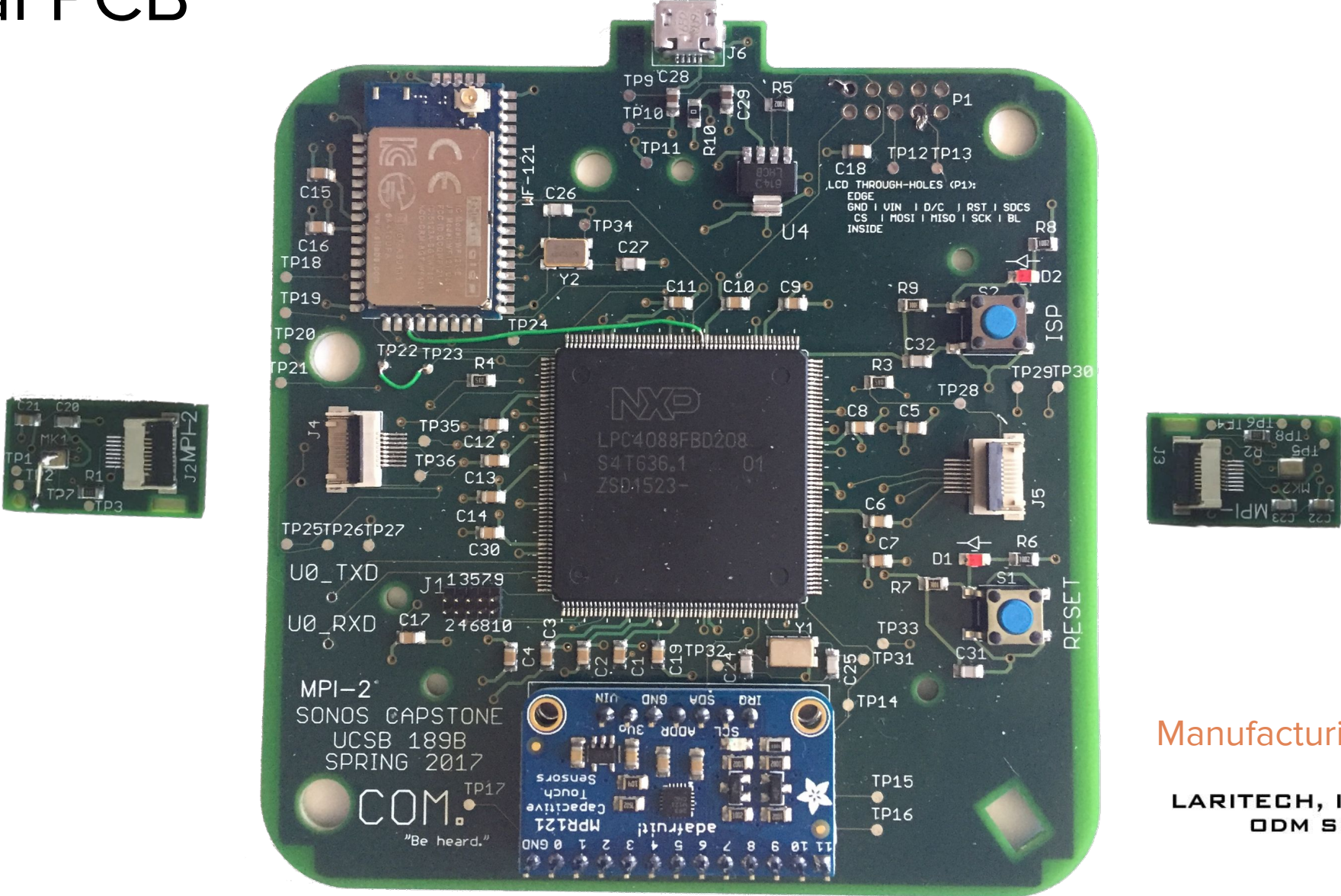
First Spin PCB



Manufacturing and rework sponsored by



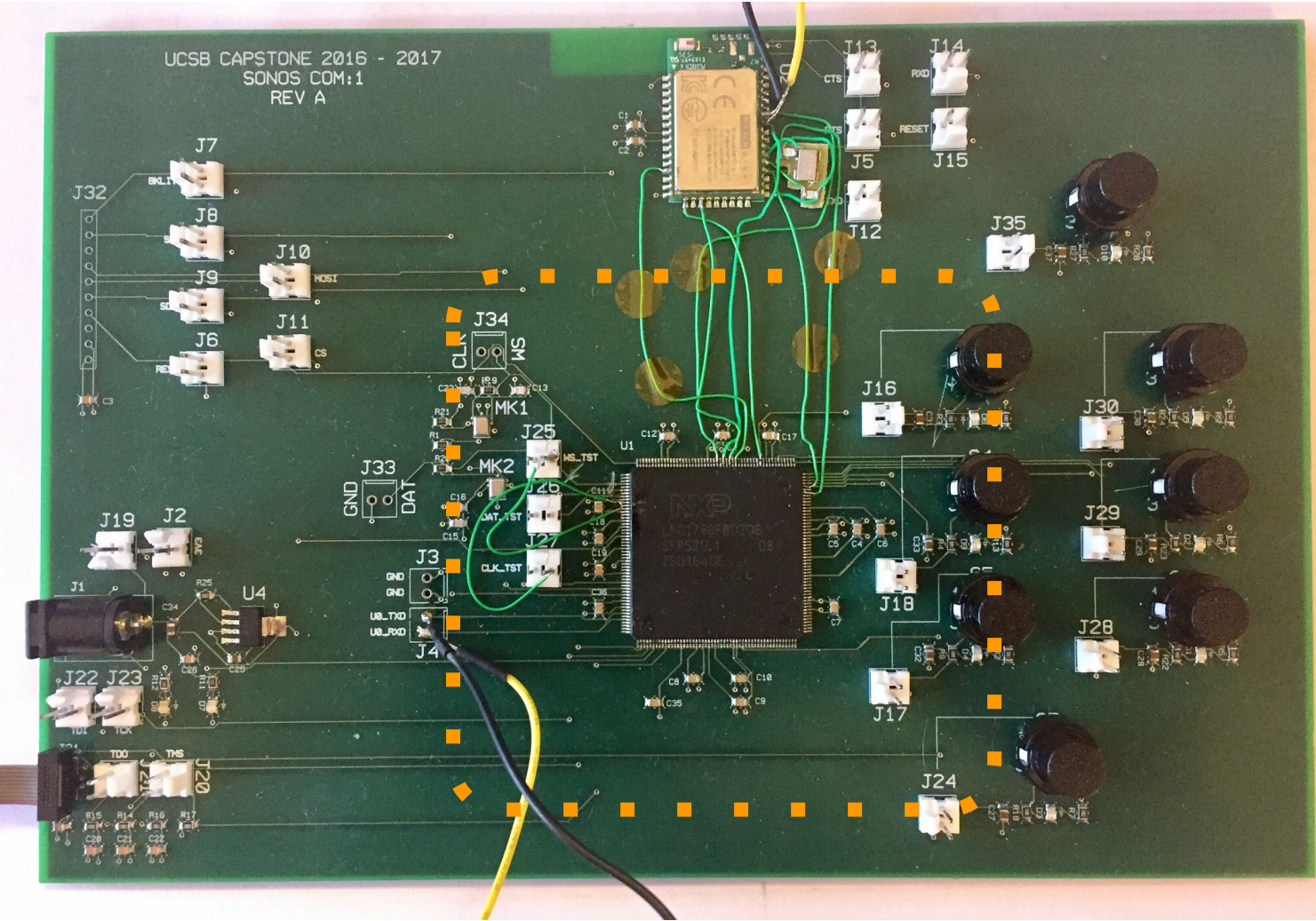
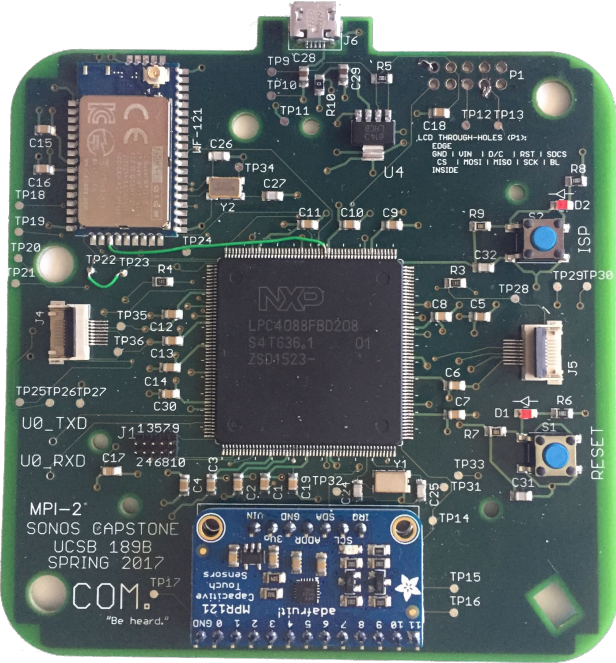
Final PCB



Manufacturing sponsored by



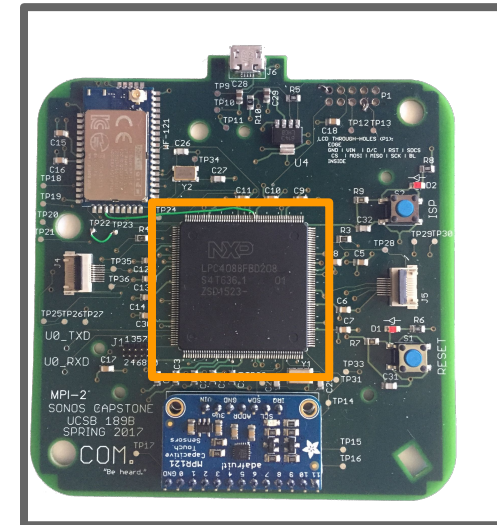
Comparison



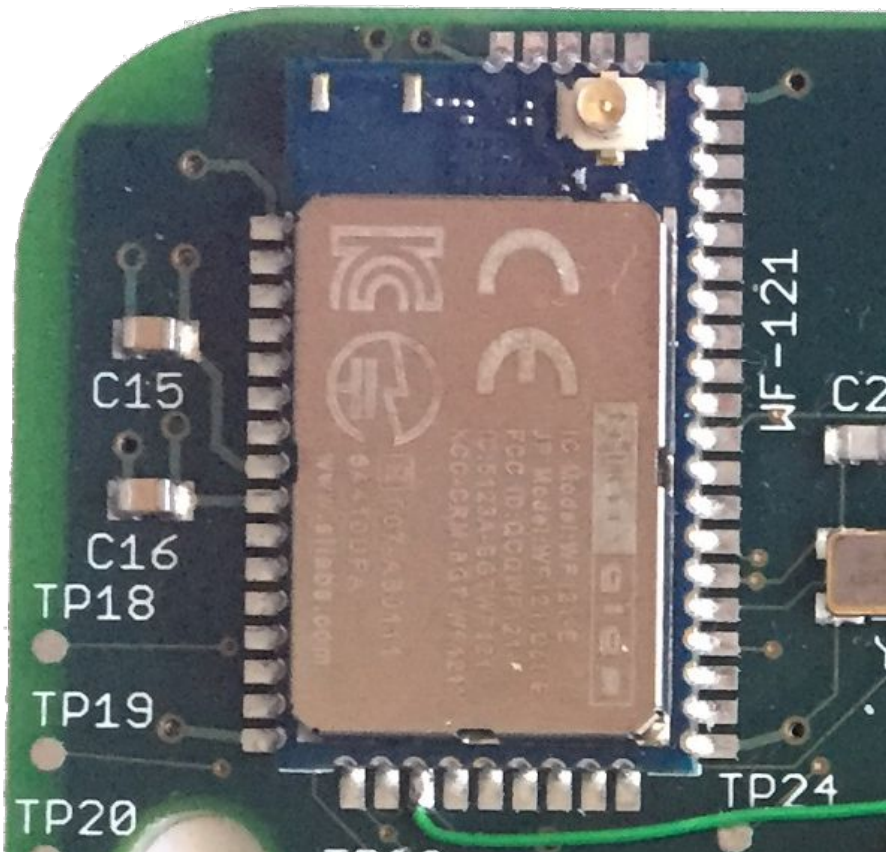
MCU - NXP LPC4088



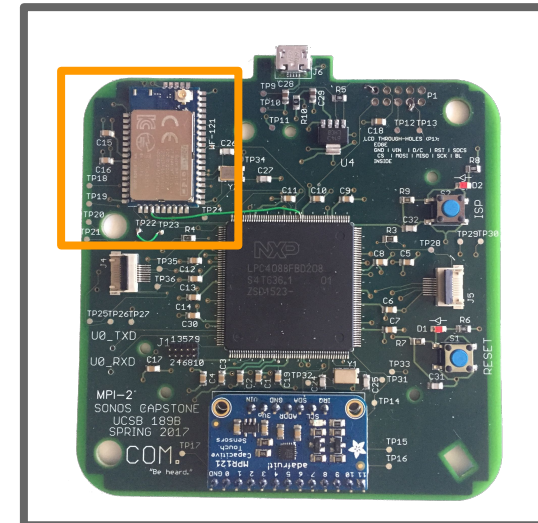
- ARM Cortex-M4 based digital signal controller.
- Features utilized
 - Three UARTs (Wifi/ISP)
 - I2S Rx (Mics)
 - I2C (Cap Touch)
 - SPI (LCD)
 - GPIO (ISP/RESET/IRQ)
- A general MCU that our instructors and TA are familiar with.
- Well Supported
- I2S Mics
- Ultimately, not the right MCU for this job. More on this in a later slide.
- Memory
 - 512 kB of flash program memory
 - up to 96 kB of SRAM data memory
 - up to 4032 byte of EEPROM data memory



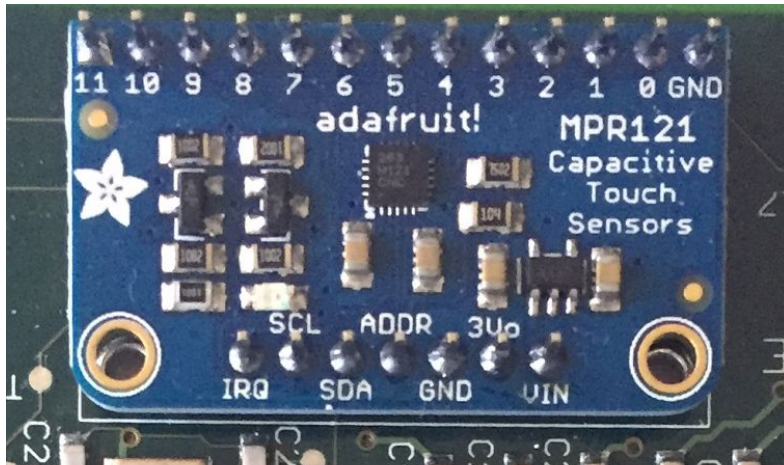
WiFi - WF121 Module



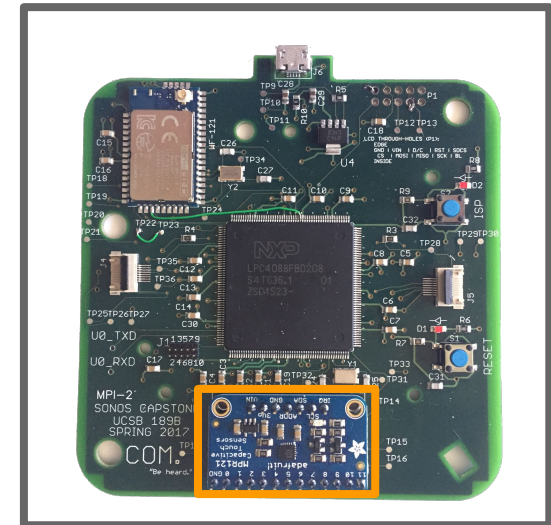
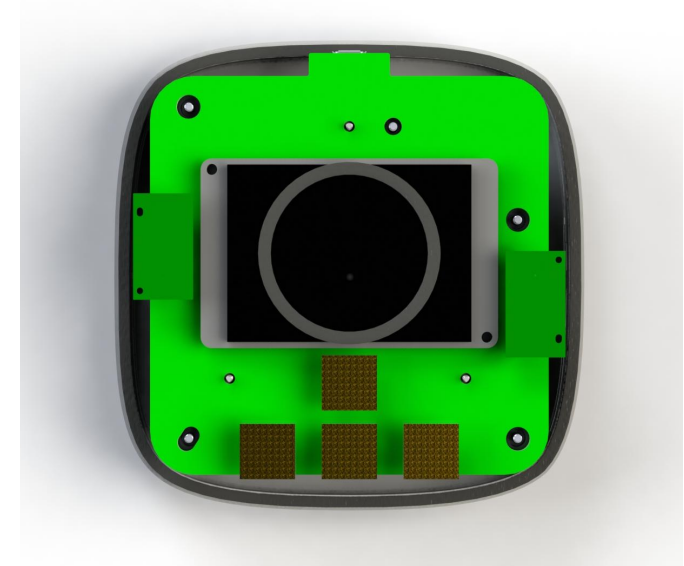
- UFL connector for external antenna.
- Two UART connections only one with flow control
- Tx and Rx lines swapped due to labeling misunderstanding
- Supports 802.11 b/g/n
- RF shield
- Why this device?
 - Easy to use software library.(bglib)
 - Supports WiFi b/g/n
 - Access Point mode and Standalone Client Mode
- Two UARTS
 - API
 - Data
- Available in two packages



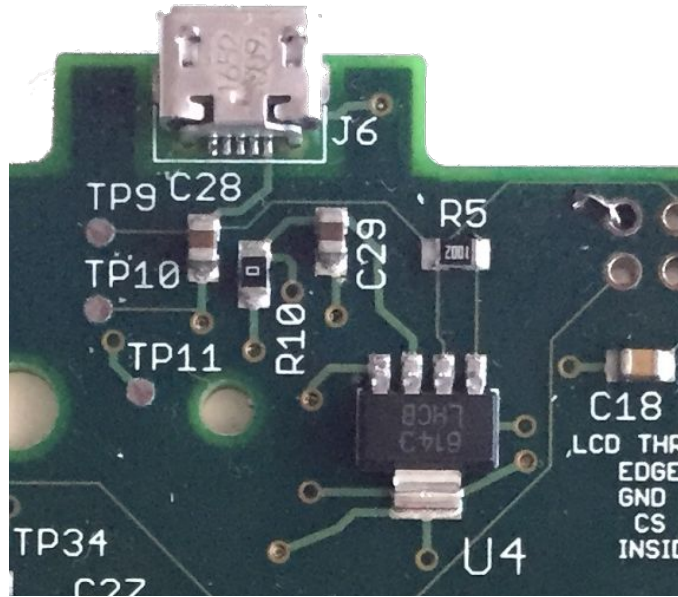
Capacitive Touch Design



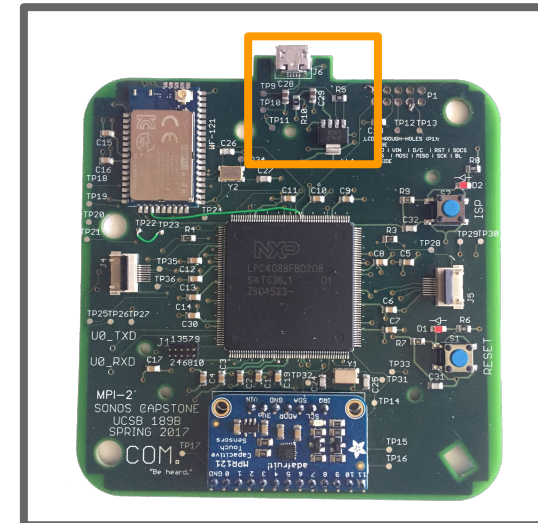
- Twelve possible input connections for capacitive control
- I2C communication
- Output IRQ signal for registering a touch
- Prevention of false triggering.
- Chose solution AD7142
 - 0 pf to 250 pf
 - 1.69 for 2,500
 - Twelve possible inputs
- 12.5 mm pads chosen as standard reflection and index finger size



Power System

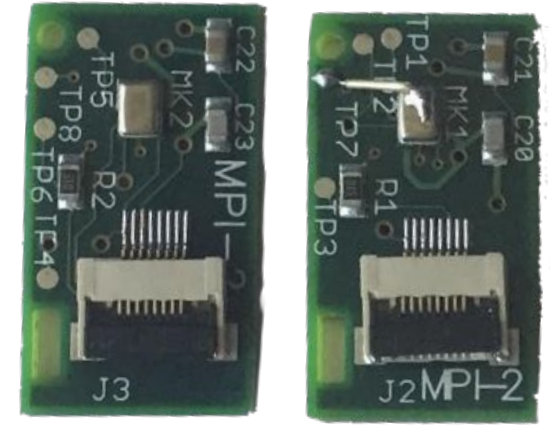


- Micro USB connector.
 - Power cable is readily available in most homes.
 - PCB extension allows for ease of physical constraints
- 5V → 3.3V Voltage Regulator
- Output Voltage Ripple Tolerance of 1.5%
- -40°C to 125°C
- Low-dropout voltage 38 mV at 150mA load current



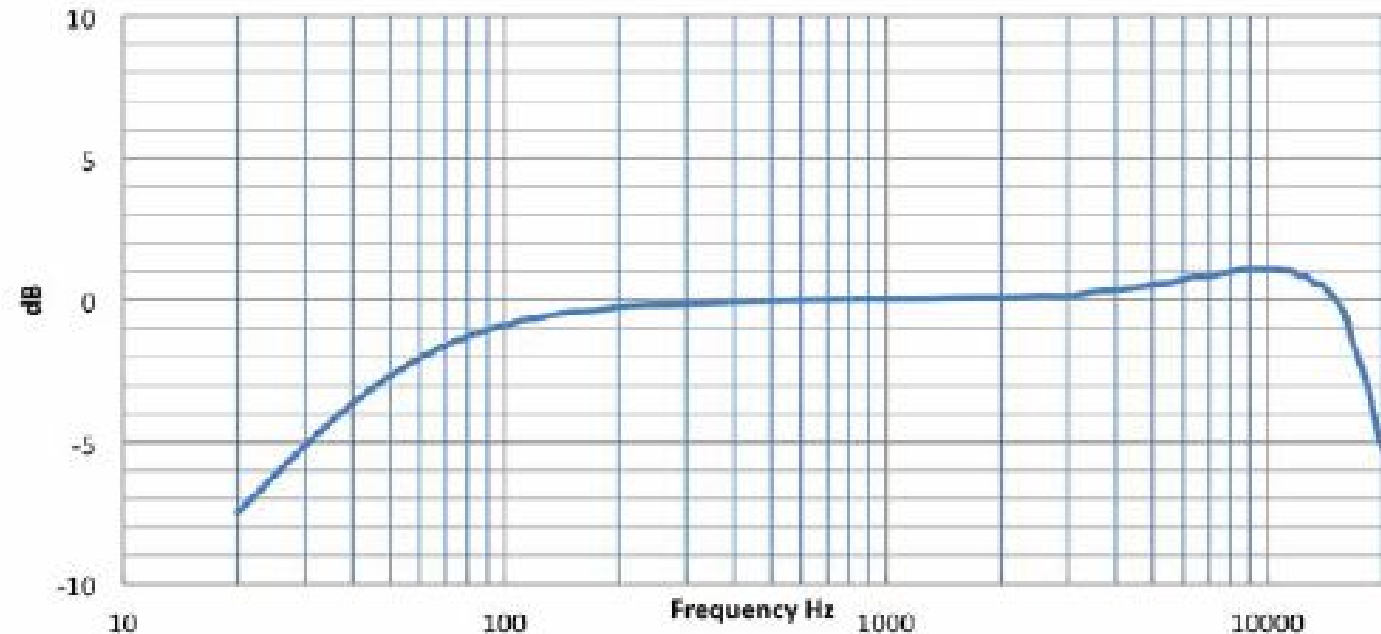
Microphones - SPH0645LM4H-B

- I2S Output
 - Decimation is done directly in the microphone and eliminate the need for an ADC or codec
 - Fewer conversions
Analog(voice) → Digital → Digital transmission → COM.
- Left and right Mic (Dual Channel)
- RF Shielded
- Omni-directional
- High SNR of 65dB(A)
- Frequency Response vs. Sensitivity (human voice: 85 Hz - 260Hz)

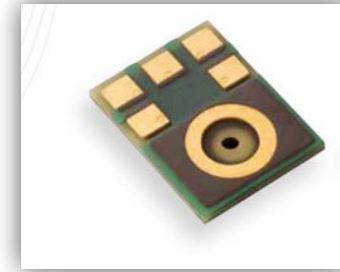


Performance Curves

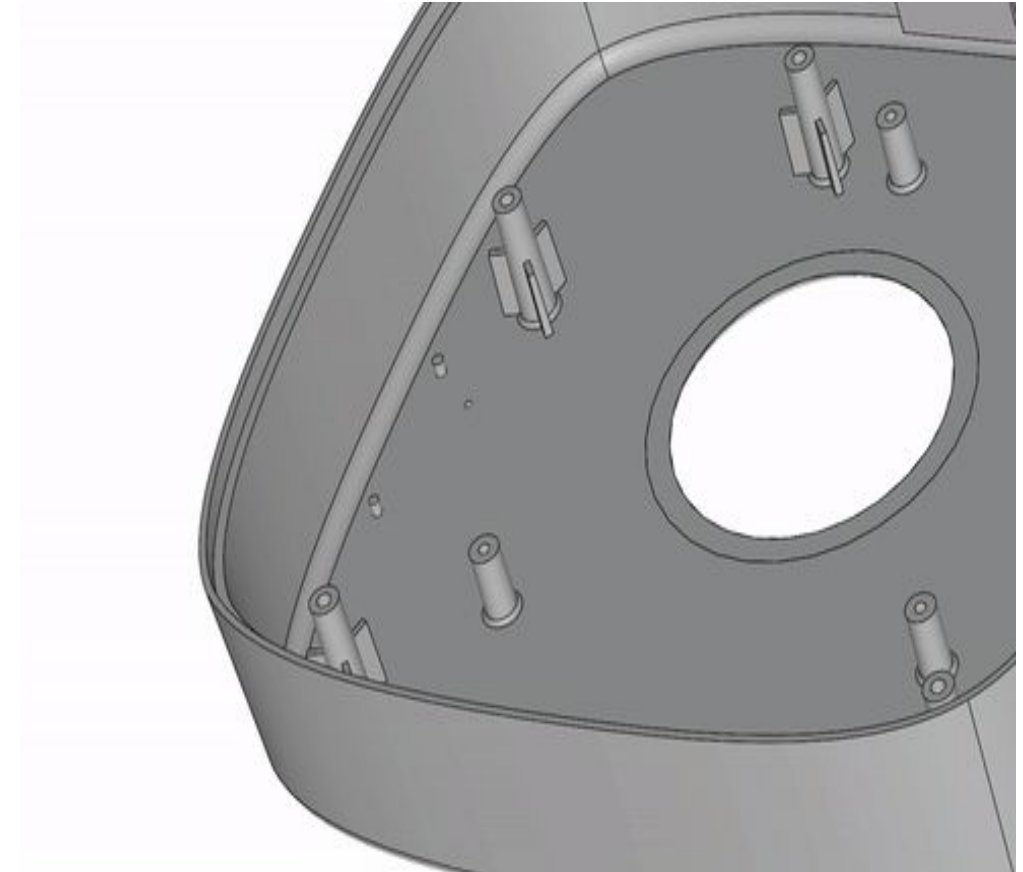
TEST CONDITIONS: 25 ±2°C, 55±20% R.H., V_{DD} = 1.8V, f_{clock} = 3.072 MHz with .1uF decoupling capacitor, unless otherwise indicated



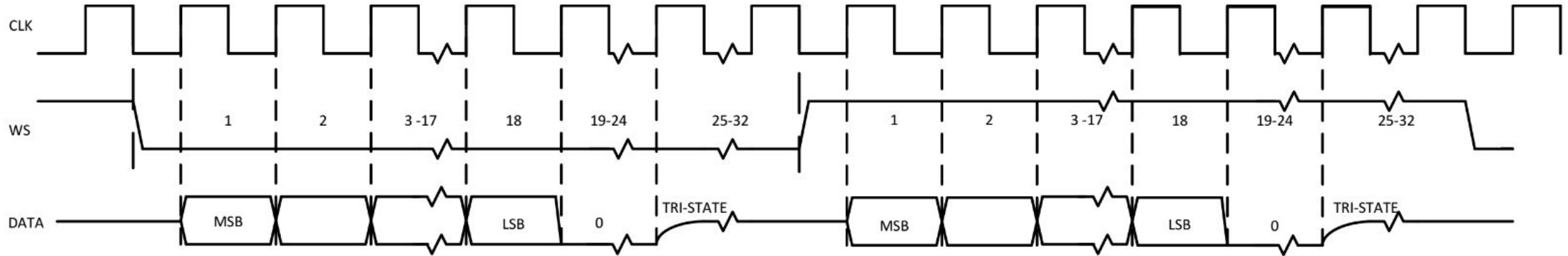
Microphones



- Perform under 3 different modes: active, sleep and powered off
- Align to the hole drilled to the outer case
- Control the data by word selecting signal and clock



Microphone Data



18 bits of resolution

8 bits of tristate

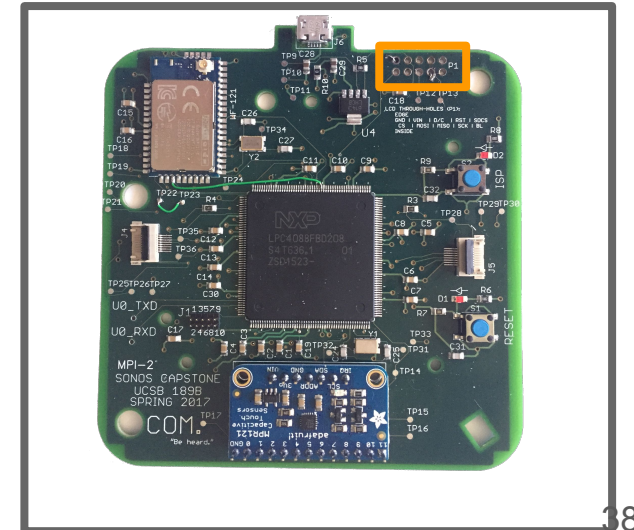
6 bits padded 0

Totalling 32 bits on each channel with with a word select frequency 1/64 of the clock frequency.

Display - 2.2" Adafruit Display



- 2.2" display chosen to provide more screen real estate in final design.
- SPI interface
- Library ported from C++ to C and LPC Open framework
- Past experience with display

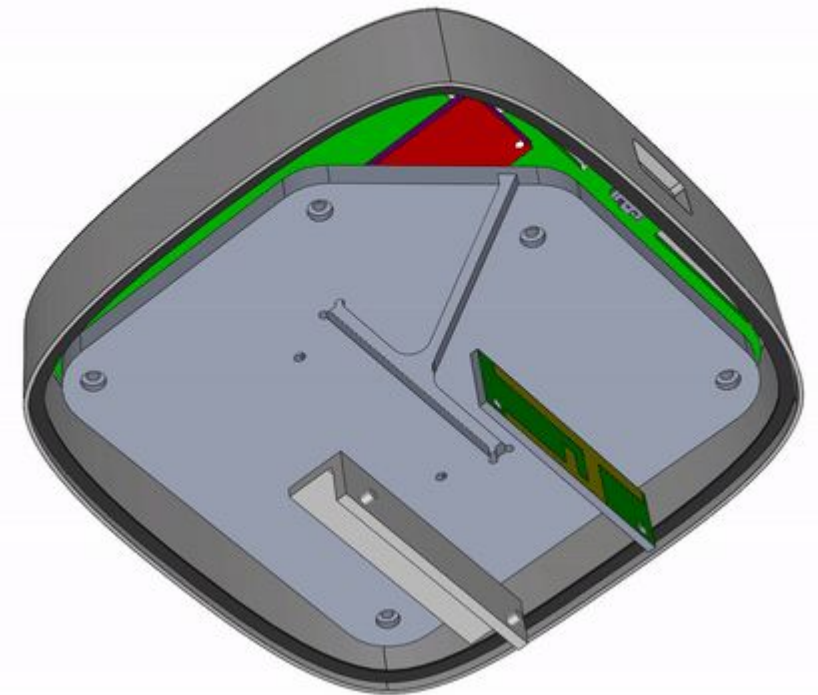


Inverted F Antenna

- Orientation, current location, and antenna choice is due to distancing the antenna away from the noise generated by the other components in our device.
- We used the Heatsink to our advantage as it shields the antenna from the rest of the components in our device. And it helps radiate the signals coming out from the antenna.

Precautions:

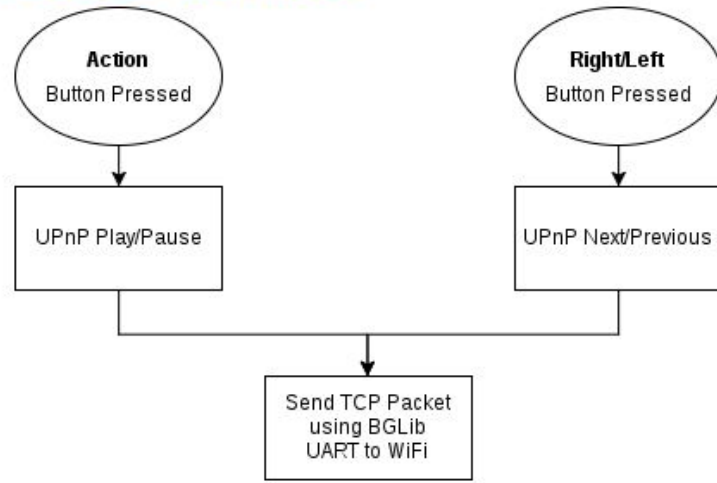
- The surfaces you place the COM. on will need to be taken into consideration. (i.e. Placing the devices on a metal surface will yield worse results than putting on a wooden surface.



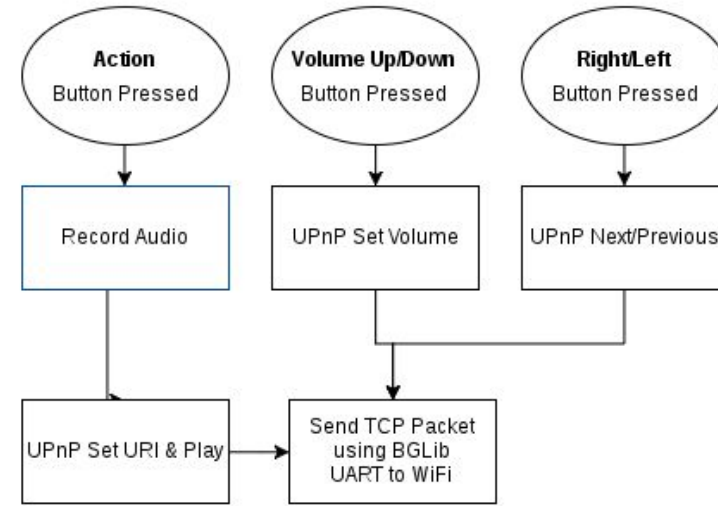


Software Design

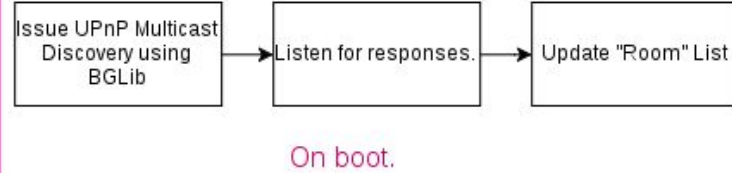
Music Control Mode



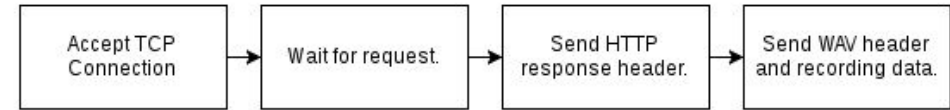
Intercom Mode



SONOS Device Discovery

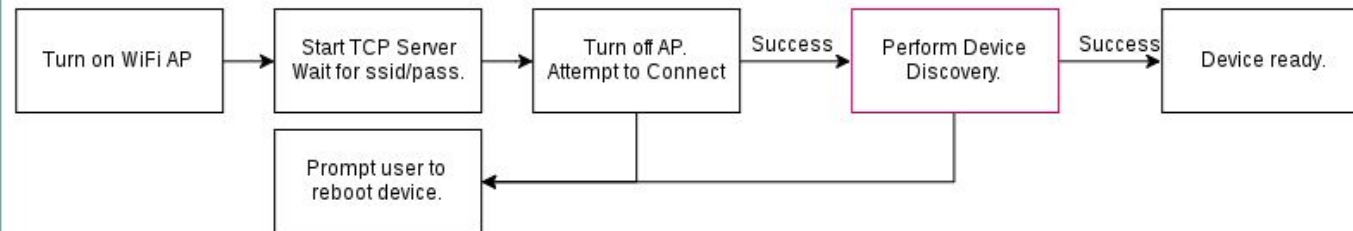


Recording Server



Always running in background.

Initial Boot / Setup



Program runs directly on
hardware.

C Language

No operating system.

LPC Open Framework.

Modular by design.

`captouch/`

`mics/`

`screen/`

`util/`

`wlan/`

`main()`

main ()

```
// abridged version
```

```
int main(void) {  
    master_init();  
    delay_init();  
    screen_init();  
    mics_init();  
    wlan_init(wlan_init_cb);  
    captouch_init(captouch_handler);
```

```
    while(1) {  
        wlan_process();  
        mics_process();  
        captouch_process();  
    }
```

```
    return 0 ;
```

```
}
```



init functions for each module

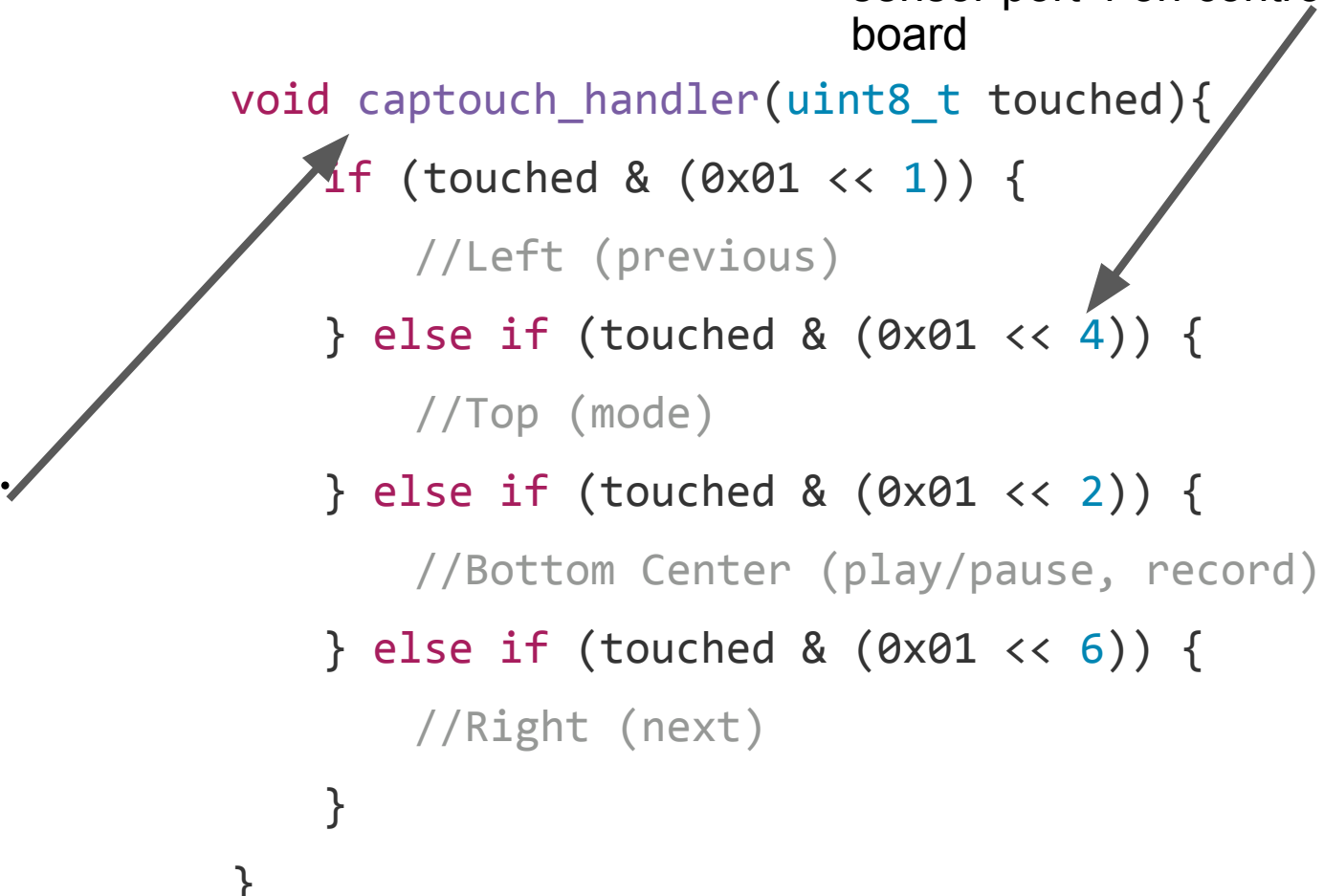
main loop

captouch/

- When you initialize this module, you provide a pointer to a function to handle touch events.
- Simple to use interface.

```
void captouch_handler(uint8_t touched){  
    if (touched & (0x01 << 1)) {  
        //Left (previous)  
    } else if (touched & (0x01 << 4)) {  
        //Top (mode)  
    } else if (touched & (0x01 << 2)) {  
        //Bottom Center (play/pause, record)  
    } else if (touched & (0x01 << 6)) {  
        //Right (next)  
    }  
}
```

sensor port 4 on controller board



`mics /`

- Samples are read as 32 bit integers via I2S. We retain **16 of the 18 valid bits of data.**
 - Necessary due to memory constraints. And we can store in increments of 8 bits.
- Peripheral to Memory DMA is used to record audio into two buffers of equal size (explanation for why two buffers in next slide).
- Currently capturing 4 32-bit samples at a time into a `uint32_t` array, then, once DMA transfer has completed, moving into a `uint16_t` array for storage, only retaining 16 most significant bits.

mics/

Why is the recording split into two buffers?

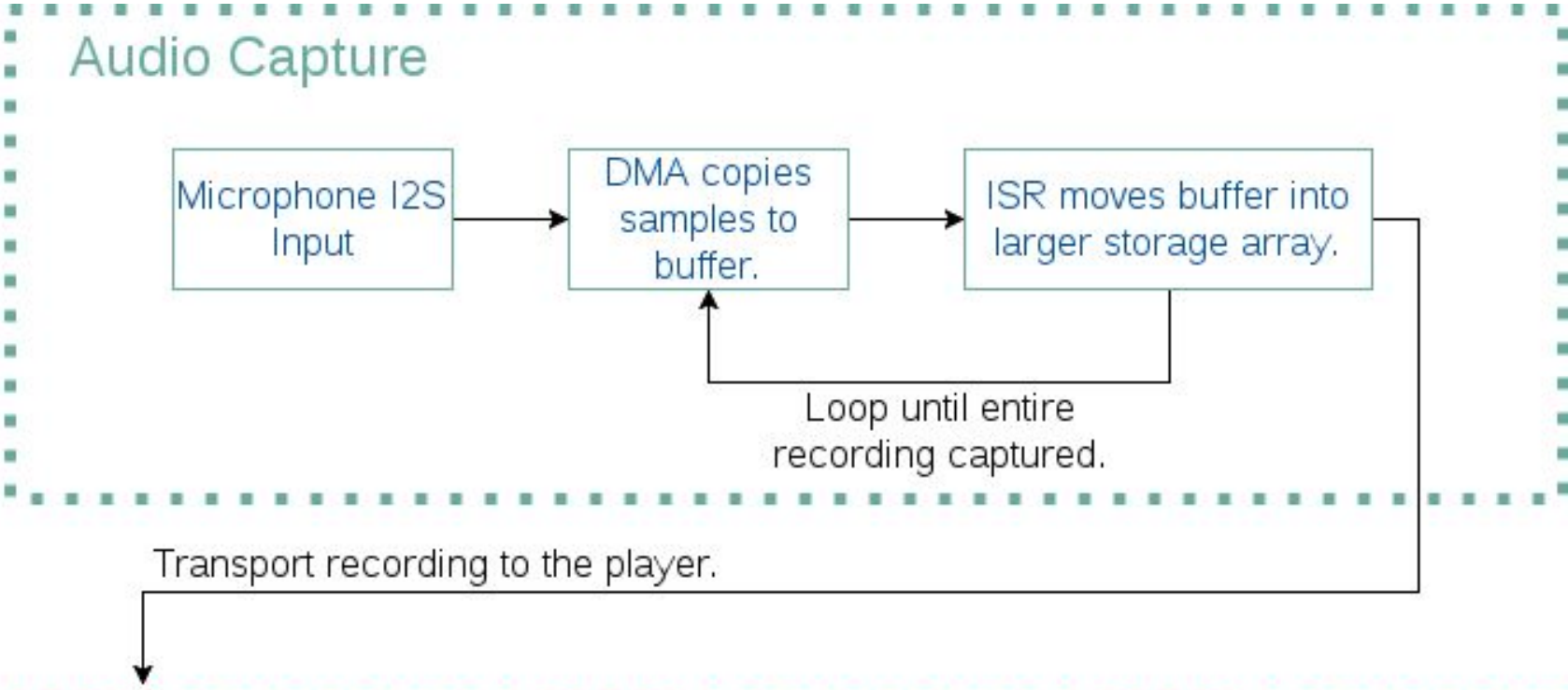
- Not enough memory in the first RAM bank. So we're using RAM and RAM2 banks on the 4088.
- I explicitly store half of the audio recording in another bank to leverage its additional storage.

```
volatile uint8_t recording[RECORDING_SIZE];
```

```
__DATA(RAM2) volatile uint8_t recording2[RECORDING_SIZE];
```

- Actual recording size is $2 * \text{RECORDING_SIZE}$.
- `#define RECORDING_SIZE 24000` (48,000 bytes total)

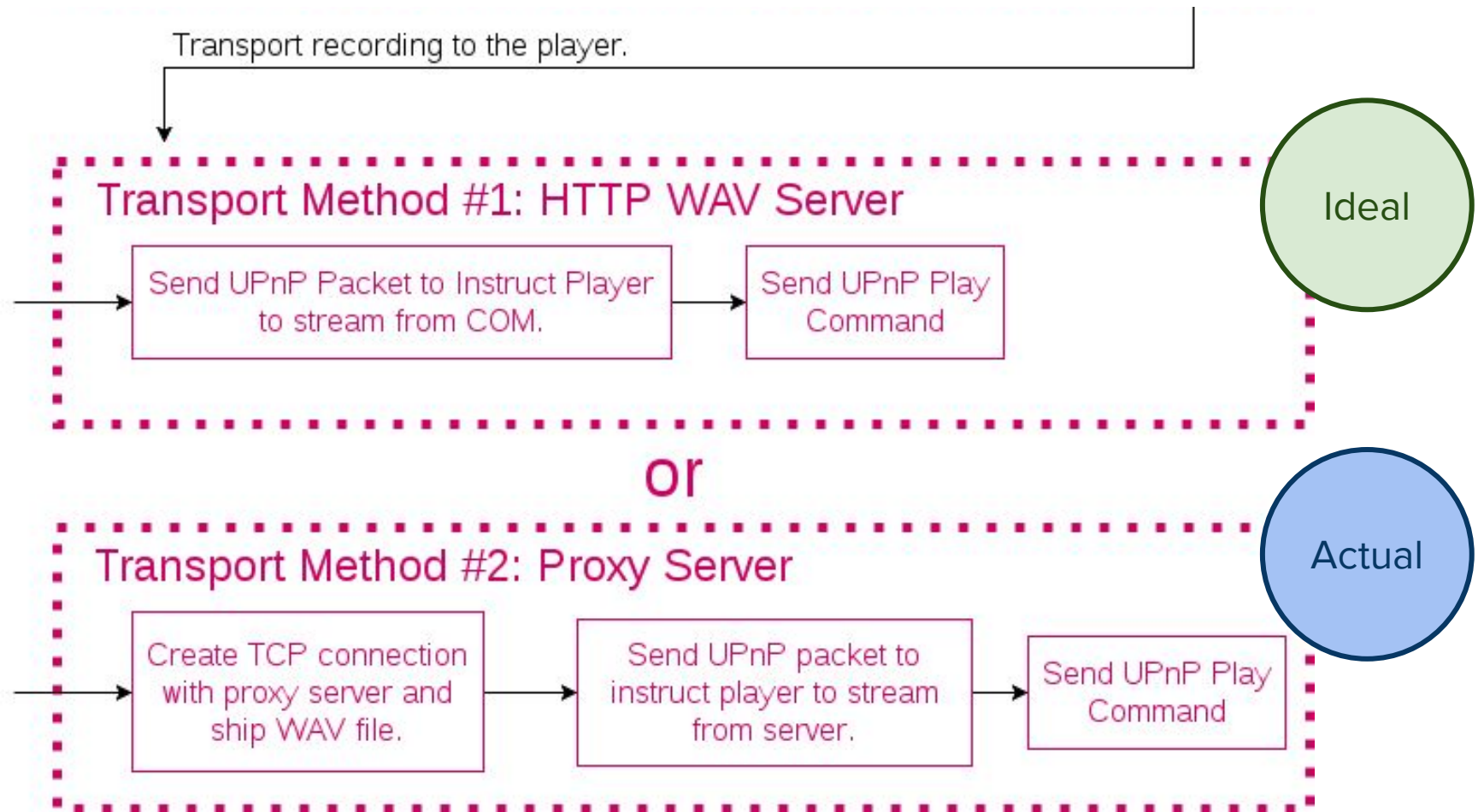
Recording Data Flow



Recording Data Flow

Both methods are supported in code.

```
#define PUBLISH_DONT_SERVE
```



Recording Playback

- Could not use Method #1 (Built-in HTTP Server)

Slower transfer speed from our device

+

player attempting to play before finished downloading

=

< 1 sec of audio played from 3 sec recording

- Method #2 (Proxy Server) as a solution for now.

wlan/

- WiFi code was designed as a state machine so that it will not block the CPU while waiting for responses and events from the WiFi module.
- UPnP
 - Handles basic UPnP commands to control SONOS devices.
 - Can issue requests to fetch device and track information.
 - Can discover devices (and rooms) on your home network.
- WAV audio file server
 - Provides an HTTP server that serves WAV file of recording.
- Generic HTTP request support.
 - Issues a custom HTTP request, and stores the response for further processing and analysis.
- Setup TCP server, used in the device setup process.

util/

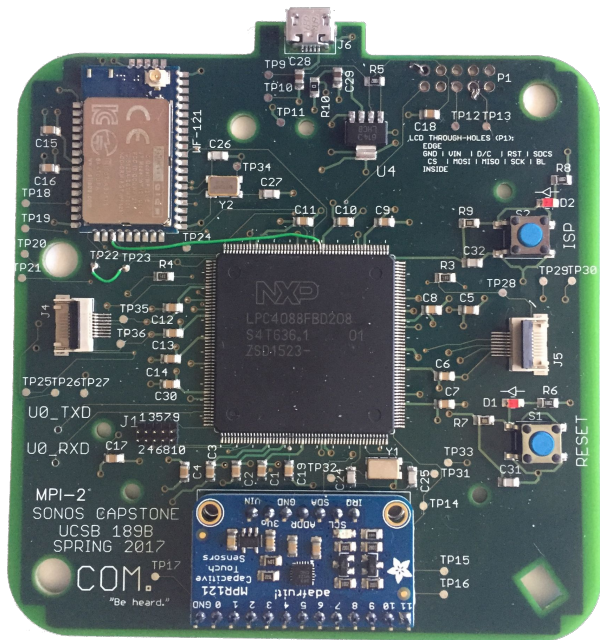
- Delay Functions
 - Utilizes the system timers
 - Extremely accurate delay function
- Queue utility functions modified from third party.

screen/

- Ported over an existing C++ Adafruit library to C and our LPCOpen platform.
- Icons
 - Bitmaps indicate which pixels need to be colored
 - X BitMap
- Text
 - There are functions that take in a string and calculate which pixels need to be colored



Summary



+

```
void mics_init(void) {  
  // mics_pin_mux_debug_pincheck(); //IF WIRES CONNEC  
  mics_pin_mux();  
  I2S_AUDIO_FORMAT_T audio_Confg;  
  audio_Confg.SampleRate = MIC_SAMPLE_RATE;  
  /* Select audio data is 2 channels (1 is mono, 2  
  audio_Confg.ChannelNumber = 1;  
  /* Select audio data is 16 bits */  
  audio_Confg.WordWidth = 32;  
  
  Chip_I2S_Init(LPC_I2S);  
  Chip_I2S_RxConfig(LPC_I2S, &audio_Confg);  
  Chip_I2S_RxModeConfig(LPC_I2S,0,0,0);  
  
  Chip_I2S_DMA_RxCmd(LPC_I2S, I2S_DMA_REQUEST_CHAN1  
  /* Initialize GPDMA controller */  
  Chip_GPDMA_Init(LPC_GPDMA);  
  /* Setting GPDMA interrupt */  
  NVIC_InitStructure.NVIC_IRQChannel = I2S_IRQn;  
  NVIC_InitStructure.NVIC_IRQChannelPrecedence = 1;  
  NVIC_InitStructure.NVIC_IRQChannelSubPriority = 0;  
  NVIC_InitStructure.NVIC_IRQChannelCmd = ENABLE;  
  NVIC_Init(&NVIC_InitStructure);  
}
```

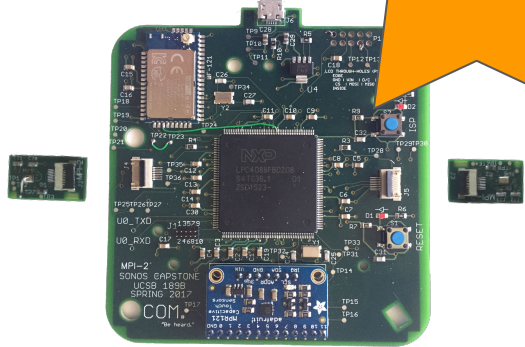
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Tangible Outcomes

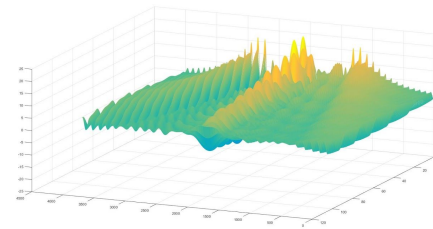
CE/EE



Hardware



Physical Units
& Test Results



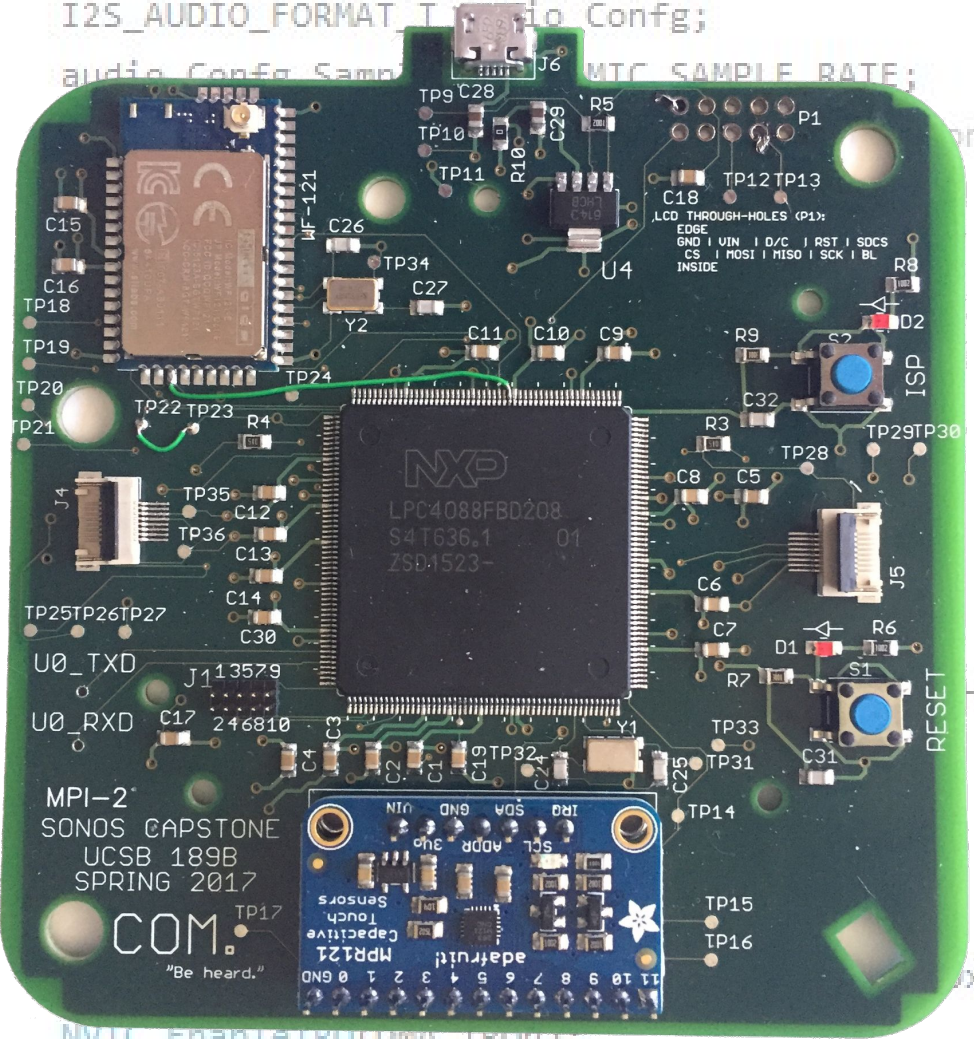
Microphone
and DSP
Research

- captouch
- mics
- screen
- util
- wlan
- app.c
- app.h

Embedded
Software

CE

```
void mics_init(void) {  
    // mics_pin_mux_debug_pincheck(); //IF WIRES CONNECTED TO MICS NO NEED TO GO THROUGH DEBUG  
    mics_pin_mux();  
    I2S_AUDIO_FORMAT_T; //io Config;  
    audio_Confg_Samp; MTC SAMPLE RATE;
```

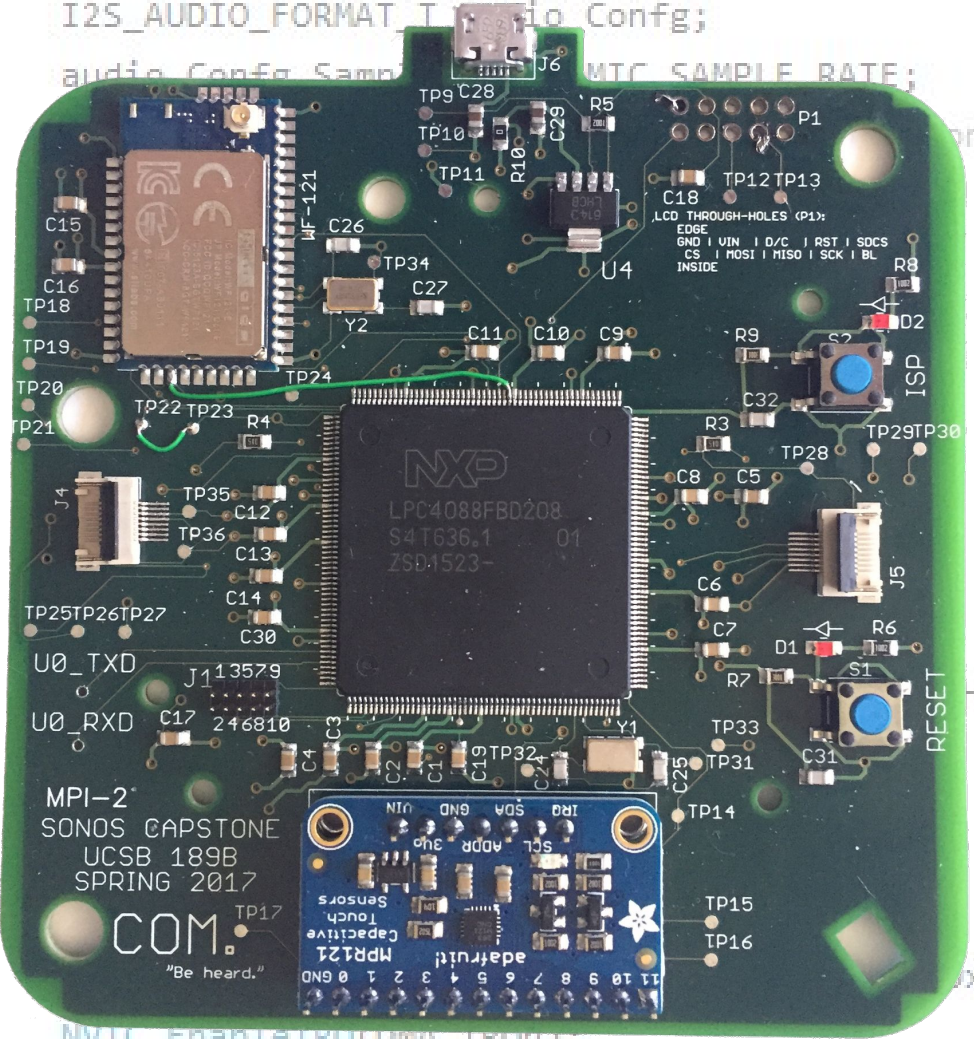


It's been designed
and built.

```
no, 2 is stereo) */  
CHANNEL_2, ENABLE, 4);  
x01));
```

```
NVIC_EnableIRQ(DMA_IRQ0);  
  
dmaChannelNum_I2S_Rx = Chip_GPDMA_GetFreeChannel(LPC_GPDMA, GPDMA_CONN_I2S_Channel_1);  
activeCb = NULL;
```

```
void mics_init(void) {  
    // mics_pin_mux_debug_pincheck(); //IF WIRES CONNECTED TO MICS NO NEED TO GO THROUGH DEBUG  
    mics_pin_mux();  
    I2S_AUDIO_FORMAT_T; //I2S audio Config;  
    audio_Confg_Samp; //MTC SAMPLE RATE;
```



It's real.

```
    no, 2 is stereo) */  
  
    CHANNEL_2, ENABLE, 4);  
  
    x01));  
    NVIC_EnableIRQ(DMA_IRQ0);  
  
    dmaChannelNum_I2S_Rx = Chip_GPDMA_GetFreeChannel(LPC_GPDMA, GPDMA_CONN_I2S_Channel_1);  
    activeCb = NULL;
```

```

void mics_init(void) {
//    mics_pin_mux_debug_pincheck(); //IF WIRES CONNECTED TO MICS NO NEED TO GO THROUGH DEBUG
    mics_pin_mux();
    I2S_AUDIO_FORMAT_T audio_Confg;
    audio_Confg.SampleRate = MIC_SAMPLE_RATE;

```



```

/* is mono, 2 is stereo) */

```

It's the COM.

```

);
QUEST_CHANNEL_2, ENABLE, 4);

```

```

NVIC_SetPriority(DMA_IRQn, ((0x01 << 3) | 0x01));
NVIC_EnableIRQ(DMA_IRQn);

```

```

dmaChannelNum_I2S_Rx = Chip_GPDMA_GetFreeChannel(LPC_GPDMA, GPDMA_CONN_I2S_Channel_1);
activeCb = NULL;

```



Thank You
Sonos, Laritech, and UCSB

Any Questions?