
Predictive Modeling of Speech

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PREDICTIVE MODELING OF SPEECH

Linear Predictive Coding (LPC):

is defined as a digital method for encoding an analog signal in which a particular value is predicted by a **linear** function of the past values of the signal

- First proposed method for encoding Human Speech US DoD
- Human speech is produced in the vocal tract which can be approximated as a variable diameter tube.
- The **linear predictive coding (LPC)** model is based on a mathematical approximation of the vocal tract represented by a tube of a varying diameter

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- The model assumes that the sound-generating mechanism is linearly separable from the intelligence-modulating vocal-tract filter.

- The precise form of the excitation depends on whether the Speech is voiced or unvoiced.
 - *Voiced speech* sound (such as /i/ in *eve*) is generated from a quasi-periodic excitation of vocal-tract.
 - *Unvoiced speech* sound (such as /f/ in *fish*) is generated from random sounds produced by turbulent airflow through a constriction along the vocal tract.

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Vocal-tract filter is represented by the all-pole transfer function,

$$H(z) = \frac{G}{1 + \sum_{k=1}^M a_k z^{-k}}$$

where

G: Gain factor

a_k : Real-value coefficient

The form of excitation applied to this filter is changed by switching between the voiced and unvoiced sounds.

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- ✓ Accurate modeling the short-term power spectral envelope plays an important role in the quality and intelligibility of the reconstructed **speech**.
- ✓ At low bit-rate **speech** coding, an **all-pole** filter is adopted to **model** the spectral information in **LPC** (linear predictive coding)-based coders.
- ✓ By minimizing the MSE between the actual speech samples and the predicted ones, an optimal set of weights for an all-pole (synthesis) digital filter can be determined

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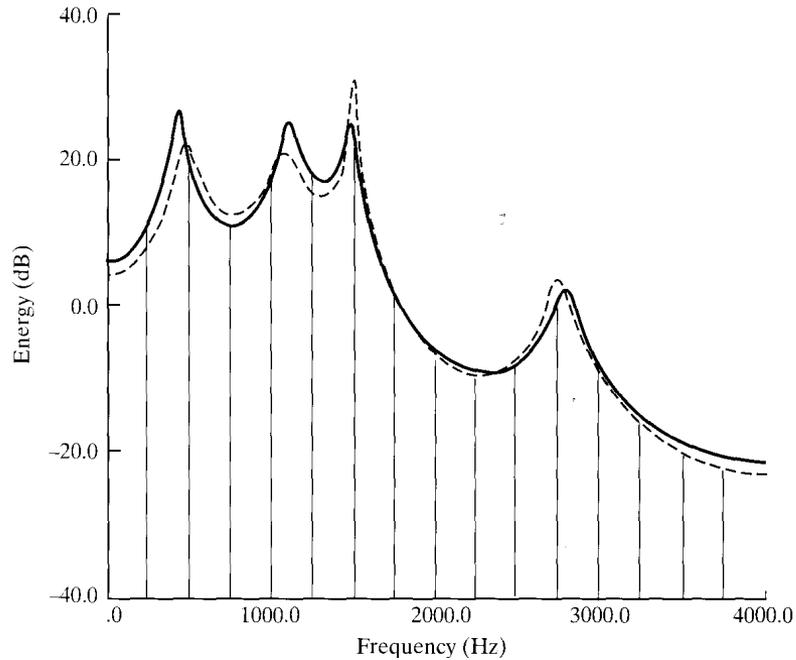
Assuming an “all-pole” model, irrespective of speech signal envelope we are trying to estimate:

- If sound is unvoiced, usual LPC method gives “good estimate” of filter coefficients a_k
- If sound is voiced, usual LPC method gives a “biased estimate” of a_k with the estimate worsening as the pitch increases (error criterion being MSE)

Example: This example illustrates the limitations of standard all-pole modeling of periodic waveforms. Specifications are:

- All-pole filter order, $M = 12$
- Input Signal: periodic pulse sequence with $N=32$

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- The solid line is the original 12-pole envelope, which goes through all the points.
- - - The dashed line is the 12-pole linear predictive model for N=30 spectral lines

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El-jaroudi and Makhoul used “*Itakura-Saito distance measure*” as “**error criterion**” to overcome this problem to develop a new model called “*discrete all-pole model*”.

Itakura-Saito distance measure:

Let $u(n)$ be a real-valued, stationary stochastic process, it's Fourier Transform U_k is:

$$U_k = \sum_{n=0}^{N-1} \left(u_n e^{-jn\omega_k} \right) \quad k = 0, 1, 2, \dots, N-1$$

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The auto-correlation function of $u(n)$ for lag m is:

$$r(m) = \frac{1}{N} \sum_{k=0}^{N-1} (s_k e^{jn\omega_k}) \quad k = 0, 1, 2, \dots, N-1$$

where

$$s_k = \sum_{m=0}^{N-1} (r(m) e^{-jn\omega_k}) \quad k = 0, 1, 2, \dots, N-1$$

Let vector \mathbf{a} denote a set of *spectral parameters* as:

$$\mathbf{a} = [a_1, a_2, \dots, a_M]^T$$

Note: See p.no.189-191 in textbook for proof

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Itakura-Saito distance measure is given by:

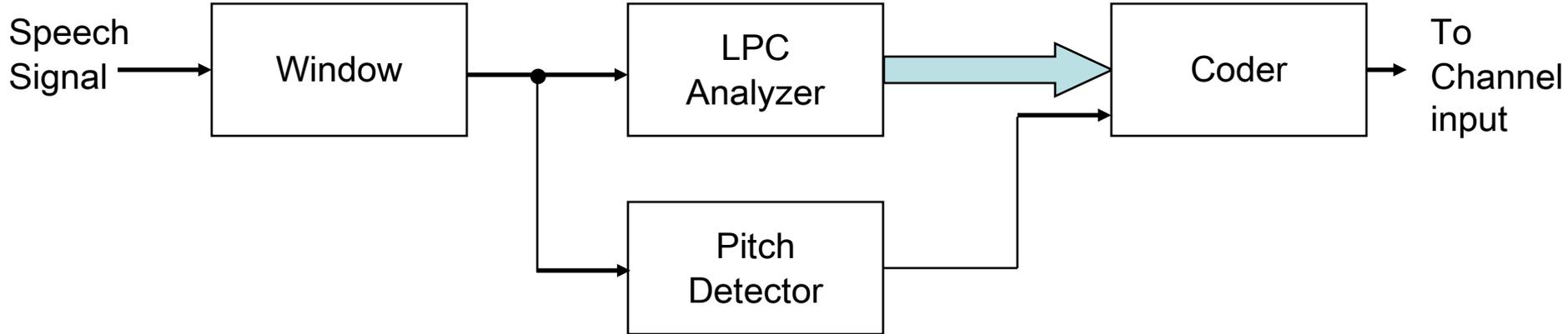
$$D_{IS}(a) = \sum_{k=0}^{N-1} \left(\frac{|U_k|^2}{S_k(a)} - \ln \left(\frac{|U_k|^2}{S_k(a)} \right) - 1 \right)$$

The time-reversed impulse response $h(-i)$ of the discrete frequency-sampled all-pole filter can be obtained from the relation of predictor coefficients to the auto-correlation as:

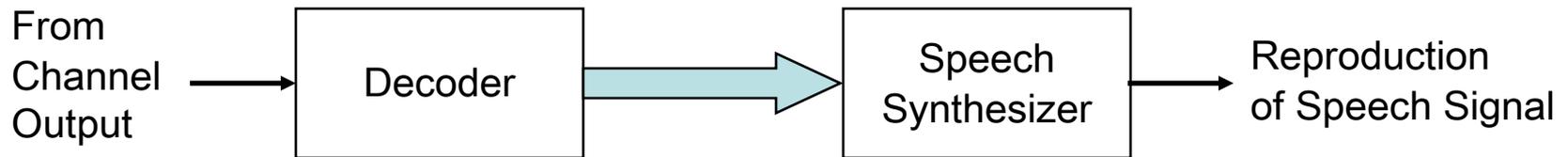
$$\hat{h}(-i) = \sum_{k=0}^M a_k r(i-k)$$

LPC Vocoder

LPC system for digital transmission and reception of speech signals over a communication channel



(a)



(b)

Block diagram of LPC Vocoder : a) Transmitter b) receiver

LPC Vocoder

Transmitter:

- Applies window (typically, 10 to 30 ms long) to the input
- Analyzes the input speech block by block
 - Performs Linear prediction
 - Pitch Detection
- Finally, following parameters are encoded:
 - Set of coefficients computed by LPC Analyzer
 - The Pitch Period
 - The Gain parameter
 - The voiced-unvoiced parameters

LPC Vocoder

Receiver:

Performs the inverse operations on the channel output:

- Decode incoming parameters
- Synthesize a speech signal from the parameters